

Assessing the Compatibility of Microwave Geodetic Systems

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Overview

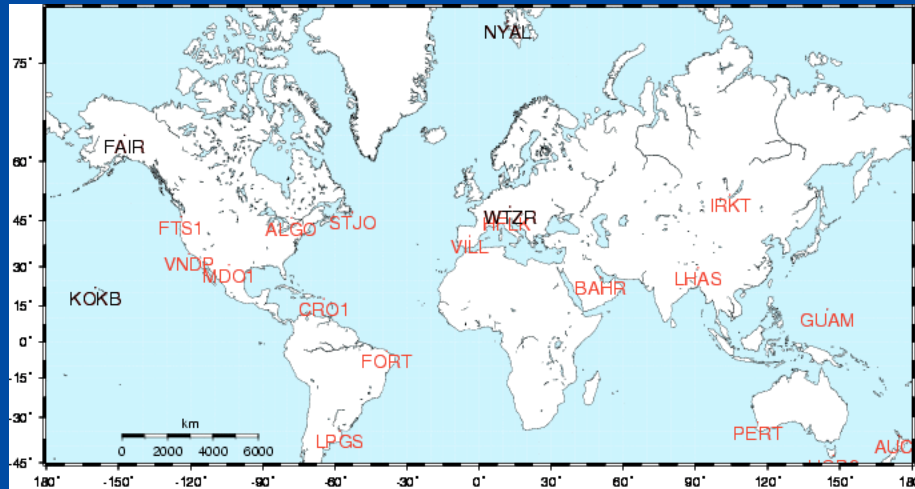
- Examine the compatibility of VLBI and GPS systems by comparing clock and atmospheric delay estimates from the two systems
- Data Analyzed:
 - End of the CONT96 VLBI experiments
 - Common stations: Fairbanks, Wettzell, Kokee, Nyales20. No GPS at NRAO station.
 - Additional 20 global stations used in GPS analysis

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VLBI and GPS Network



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Analysis Technique

- VLBI: CALC+SOLVK Kalman filter
 - Clock process noise consistent with 10^{-14} Alan standard deviation at 1000 seconds; Quadratic terms removed a priori.
 - Atmospheric process noise: Derived from delay-rate variance: Typical random walk values 10 mm/sqrt(hr); variations of factor of three about this value
 - Constant zenith delay based on station height and zero water vapor

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Analysis Technique

- GPS: GAMIT program
 - Clocks estimated epoch-by-epoch relative to Fairbanks/Gilcreek clock
 - Phase clocks aligned with clocks from pseudo-range estimates
 - Atmospheric delay estimated with piece-wise linear function with nodes every 2-hours. Stochastic noise 20 mm/sqrt(hr)
 - Constant apriori zenith delay.

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Some effects that might be expected: Clock effects

- GPS is controlled by 10.23 MHz oscillators
- On the Earth's surface these oscillators are set to $10.23 \times (1 - 4.4647 \times 10^{-10})$ MHz (39,000 ns/day rate difference)
- This offset accounts for the change in potential and average velocity once the satellite is launched.
- The first GPS satellites had a switch to turn this effect on. They were launched with "Newtonian" clocks

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Corrections terms

- Propagation path curvature due to Earth's potential (a few centimeters)

$$\Delta\tau = \frac{2GM}{c^3} \ln \left[\frac{R_r + R_s + \Delta\tau}{R_r + R_s} \right]$$

- Clock effects due to changing potential

$$\Delta\tau = \frac{\sqrt{GM}}{c^2} e\sqrt{a} \sin E$$

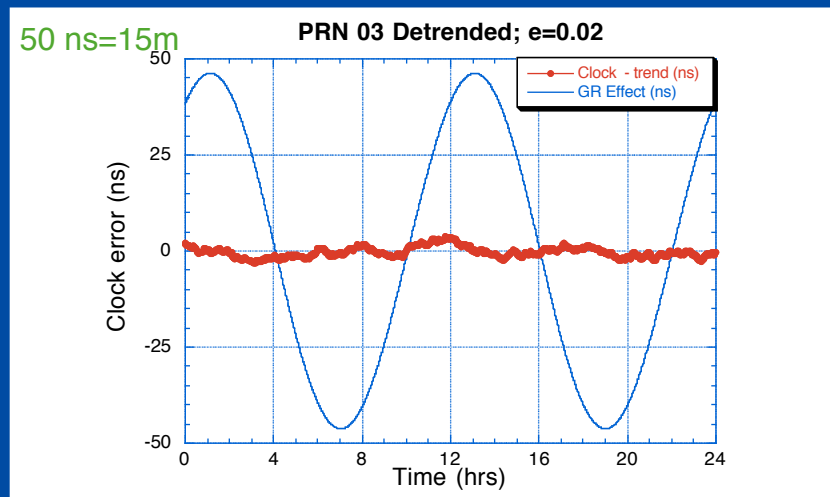
- For e=0.02 effect is 47 ns (14 m)

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Relativistic Effects (SA off)



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Comparisons

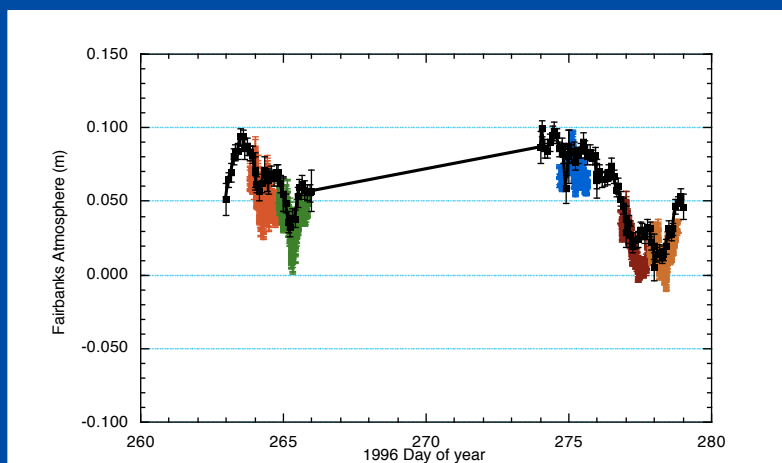
- Atmospheric delays:
 - Easiest comparison because a priori zenith delay chosen as constant and the same a priori used for VLBI and GPS
- Clocks:
 - Clocks are more difficult to compare because:
 - No absolute standard for either system (show clocks relative to Fairbanks/Gilcreek)
 - VLBI has different quadratic removed each day. Clocks relative to ensemble
 - GPS also referred to Fairbanks. Only linear trend removed each day.

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Fairbanks Atmospheric delays

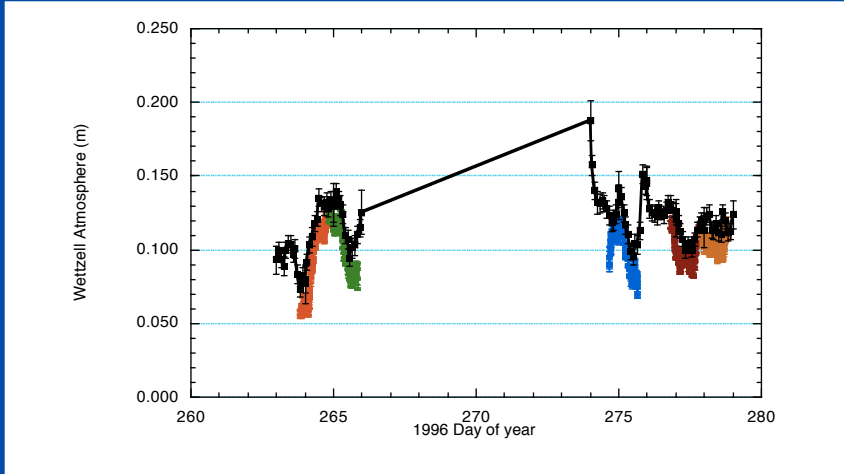


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Wetzell Atmosphere

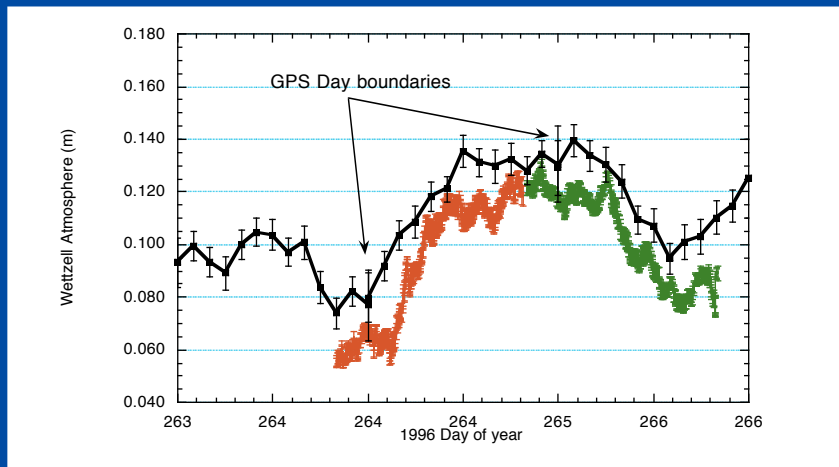


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Zoom of Wetzell (Sep 19-20)

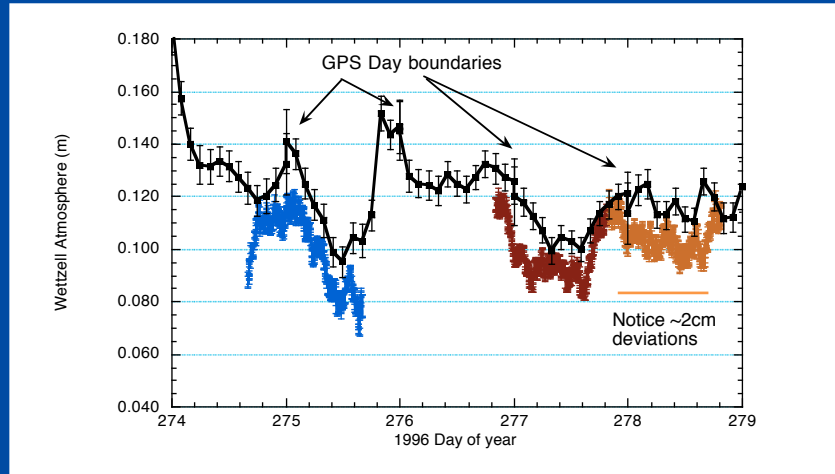


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Zoom Wettzell (Sept 30-Oct 2)

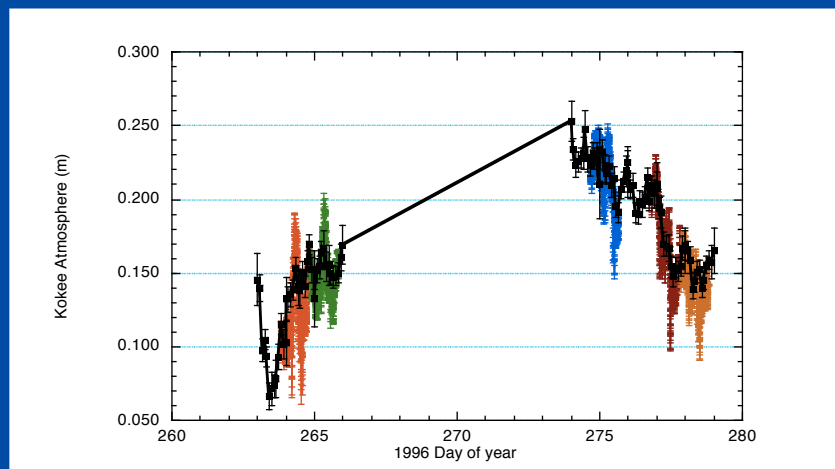


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KOKEE Atmosphere

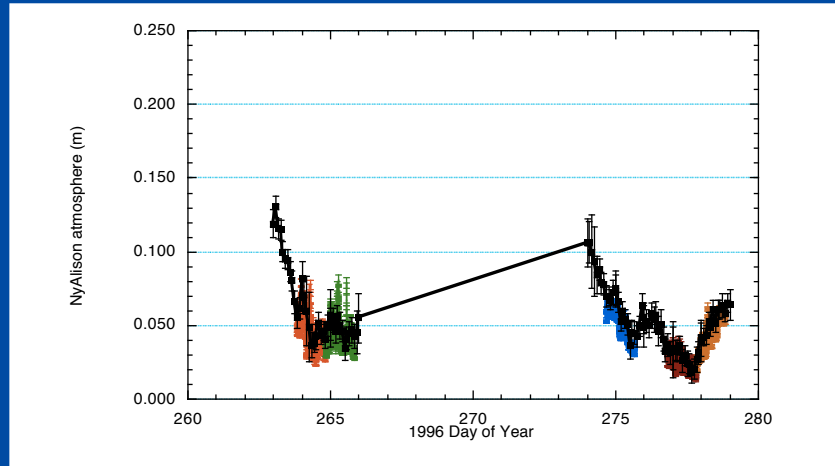


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NyAlison Atmosphere

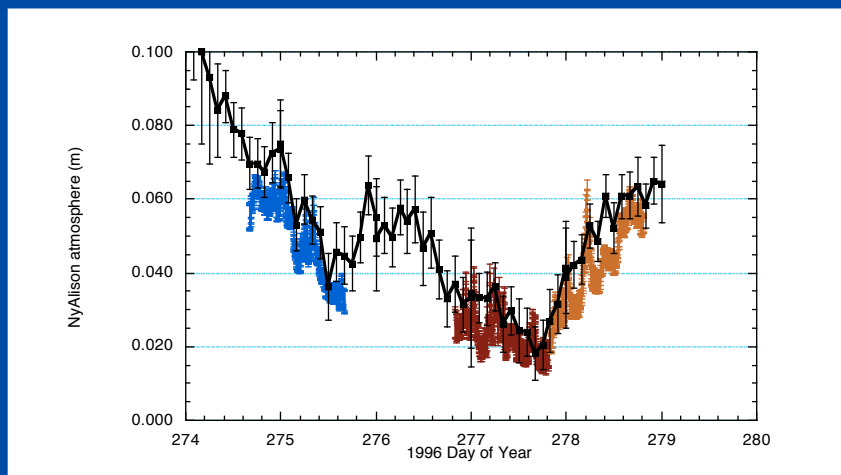


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Zoom of NyAlison (Sep 30-Oct 2)



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Clock comparisons

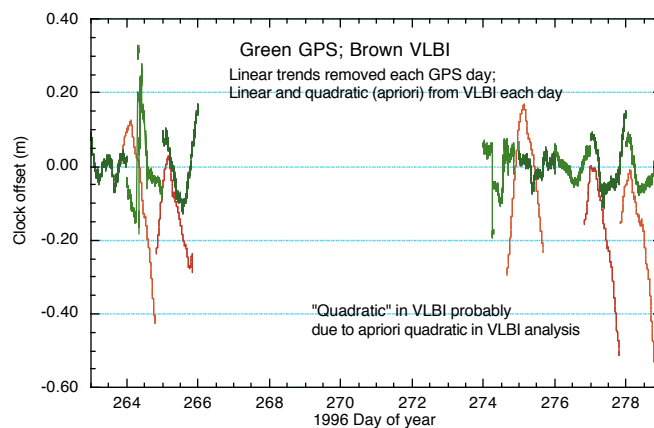
- Clock comparisons are “complicated” by the removal of trends from VLBI results (can be corrected but currently time-consuming).
- Absolute offsets can not be compared because of VLBI group delay ambiguities; the GPS alignment of phase and range; unknown delays in VLBI and GPS electronics
- Examine difference of Wettzell and Fairbanks clocks

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Wettzell-Fairbanks comparison

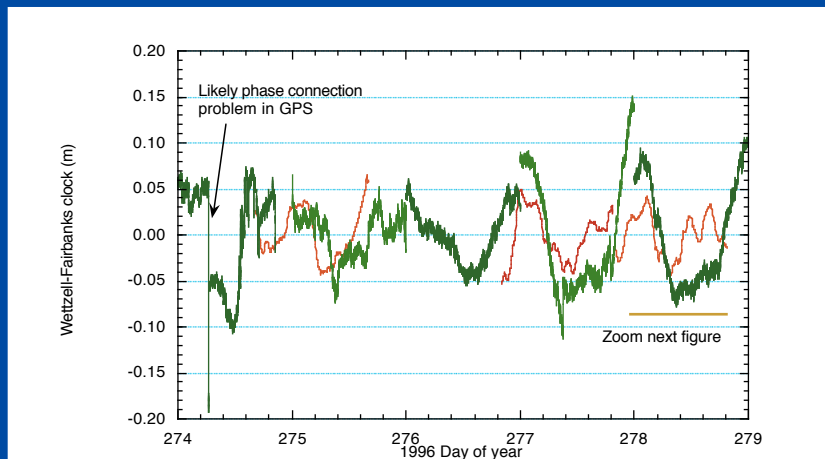


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Wettzell-Fairbanks with VLBI quadratic removed

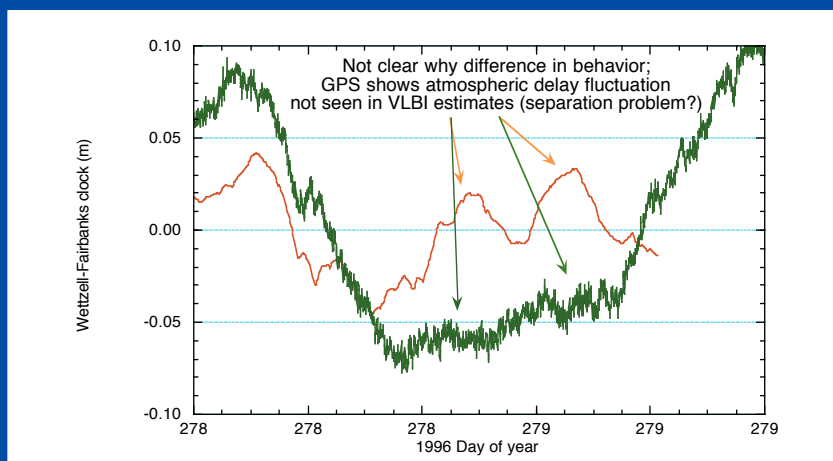


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Zoom area for Wettzell



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Conclusions

- Initial study of comparison between VLBI and GPS clock parameters and atmospheric delay estimates.
- Initial results indicate that clocks are comparable quality (no smoothing in GPS)
- Next steps:
 - Accounting for clock rates and accelerations applied to VLBI
 - More consistency in mapping functions and gradients
 - Effects of model changes in GPS (antenna phase centers) on clock comparisons
 - Time dependent process for GPS atmospheres (validation using VLBI data)
- Possible use of GPS atmospheres and clocks in the analysis of VLBI?