

Survey-mode measurements and analysis

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GAMIT-GLOBK course
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12–16 January 2015

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Measurement Strategies I: Occupation Time

Given time and personnel constraints, what are the trade-offs between between spatial and temporal density?

Ideally, you would like for the white-noise position uncertainty for an occupation to contribute to the velocity uncertainty at a level less than the usually dominant long-period correlated noise.

Typical white-noise uncertainties (Horizontal and Vertical) as a function of occupation time:

6-8 hrs: 2-2.5 mm H, 5-10 mm V

12-24 hrs: 1.0-1.5 mm H, 3-5 mm V

36-48-hrs: 0.7-1.0 mm H, 2-4 mm V

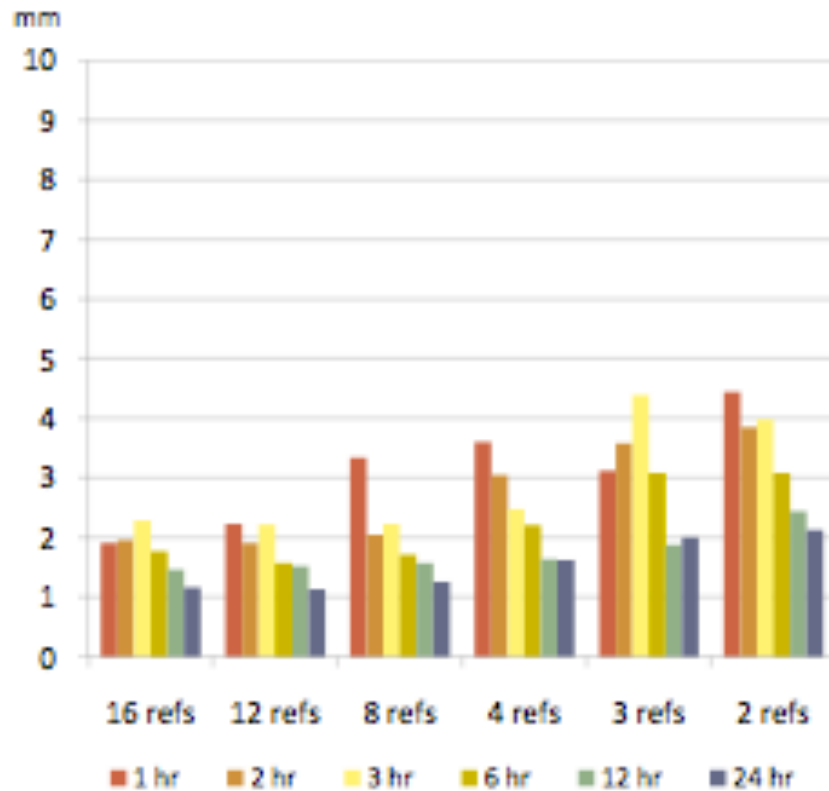
Observations over 3 or more days will give you more redundancy

Observations of 5 or more days will be necessary for mm-level vertical uncertainties

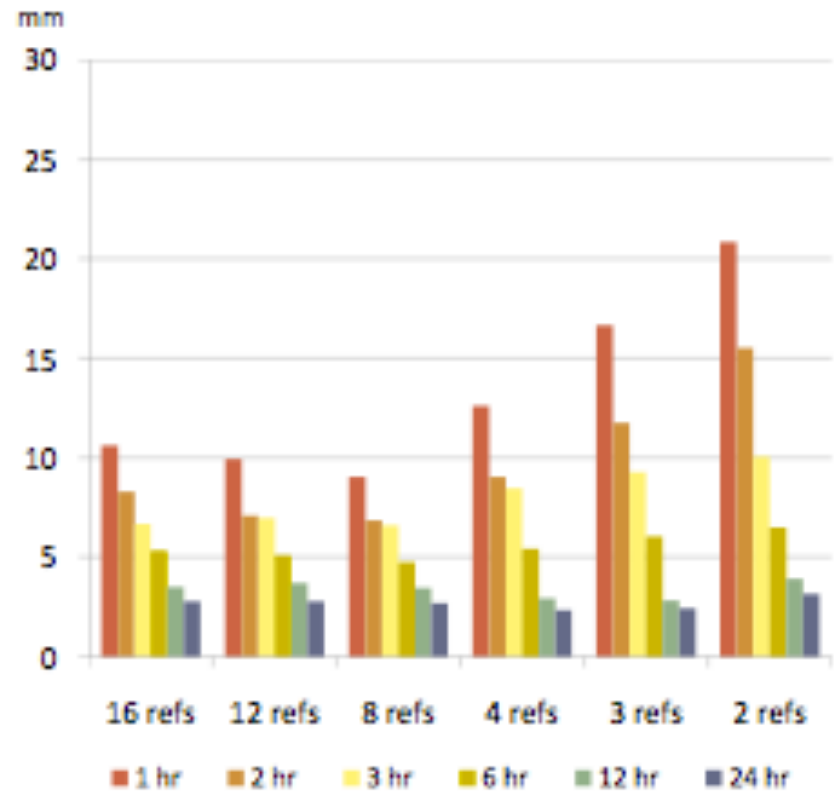
If your region has few continuous stations, you should consider running one or two survey-mode stations for the entire time of the survey to provide continuity

Precision v session length for network processing

horizontal repeatability



vertical repeatability



Measurement Strategies II: Monuments and Instrumentation

Issues in site and antenna selection :

Monument stability

Accessibility

Ease of setup

Multipath

Vandalism

- There is no clear prescription for all cases; let's look at some examples

Three primary mounting options



Spike mount



Tripod with optical or physical plummet



Site VELA in the Soloman Islands.



Tech 2000 kit.

Mast

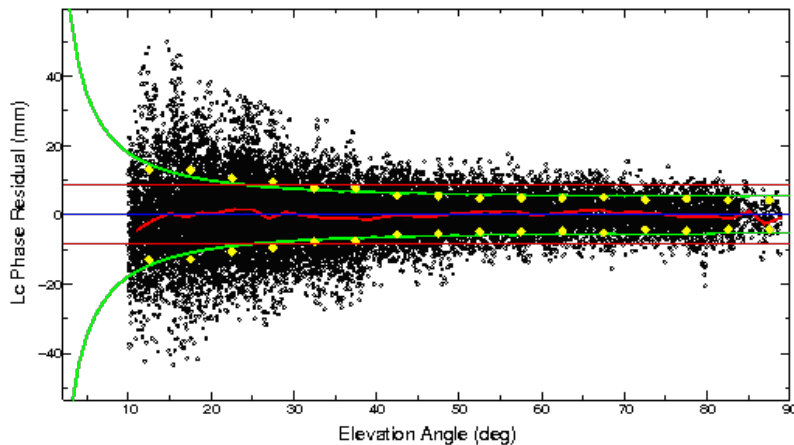
Courtesy UNAVO web page

Low mount in a good enviroment



STVP
Steven's Pass, Cascades
Range in western
Washington

18-cm spike mount



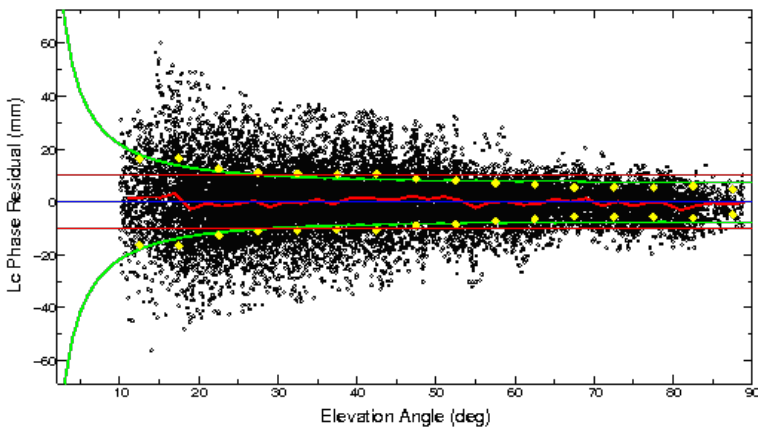
No long-term repeatability yet, but 44 hrs of observations in 2012 give formal uncertainties 0.5 mm horizontal, 3 mm vertical. Note minimal long-period signal Scattering.

Low mount in a dirty environment



B059
Roadside
meadow in
western
Washington
12.5-cm spike
mount

Two 24-hr measurements in 2012 agree at 1 mm horizontal, 4 mm though formal uncertainties 2 mm, 10mm due to high random noise (diffuse multipath or water vapor?) Note minimal long-period signal scattering. Long-term scatter 3 mm horizontal, 5 mm vertical (monument instability?)

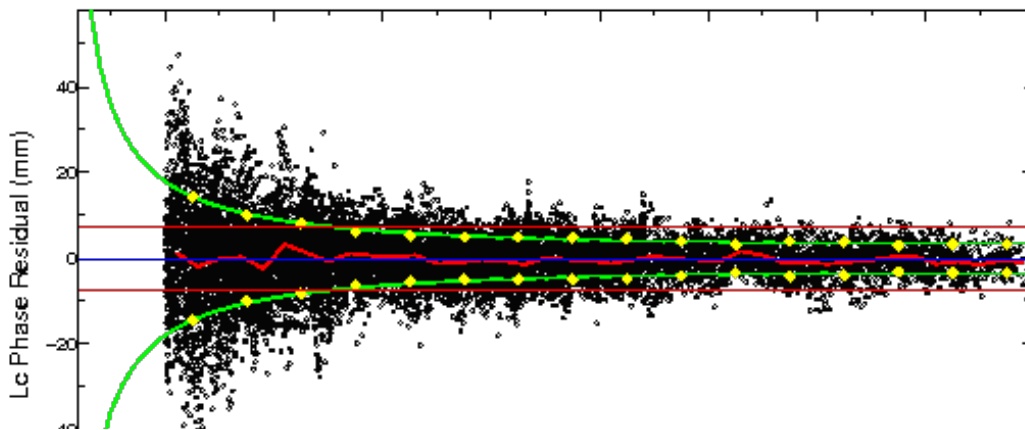


High mount in a dirty environment



C033

Old survey mark in dirt in central Washington. Tripod mount. (Train blockage was short-lived)



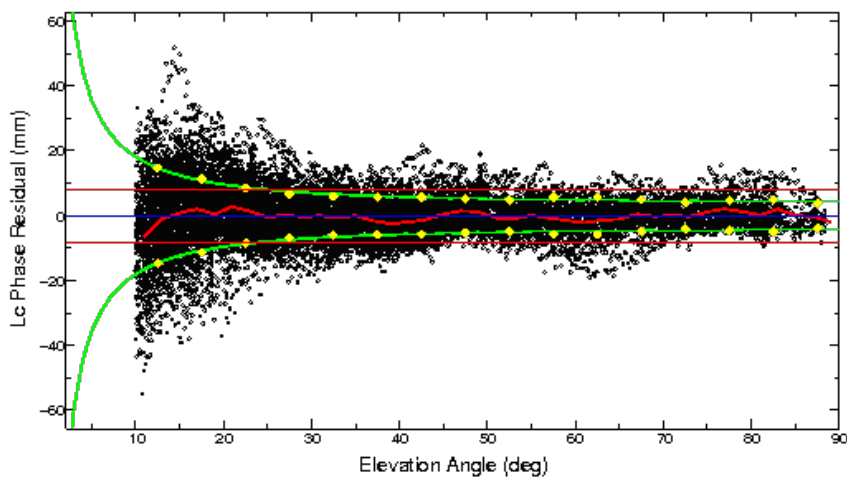
2012 19-hr session and 5-hr session agree at 1.5 mm horizontal, 3 mm vertical. Long-term repeatability 2 mm horizontal, 12 mm vertical.

Surprisingly little short-period multipath (dry dirt?)

Low mount on a slope



LYFR
Rocky river bank
in eastern
Oregon
12.5-cm spike
mount



Single 14-hr session . Long-
period multipath due to slope
and/or reflective rocks ?

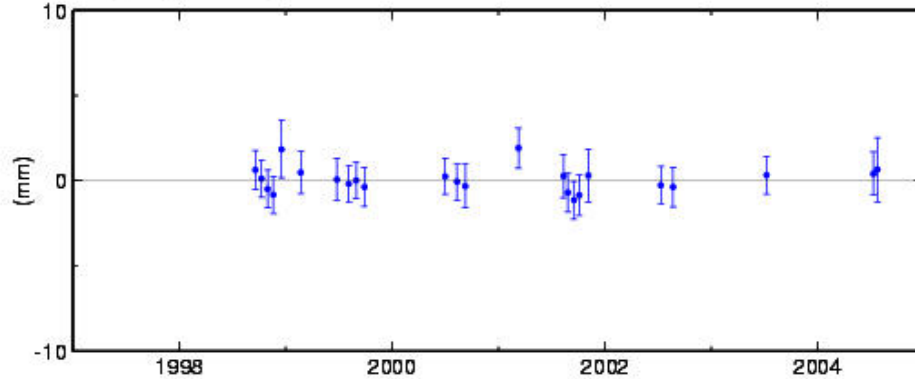
Special Characteristics of Survey-mode Data

- Editing is critical: every point counts
- Usually combined with cGPS data to provide continuity and a tie to the ITRF
- Appropriate relative weighting needed in combining with cGPS data
- Antenna meta-data may be more complicated
- Heights may be problematic if different antennas used
- Seasonal errors behave differently than in cGPS data: best strategy is to observe at the same time of the year (unlike cGPS, which has minimal seasonal sensitivity at 1.5, 2.5, 3.5 ...years total span)

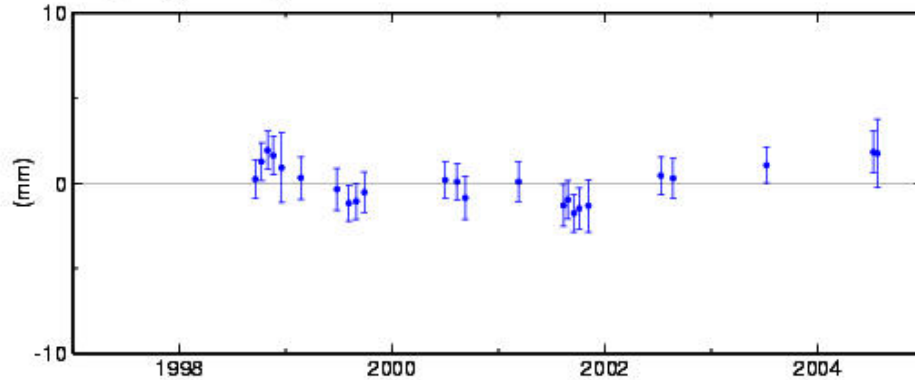
Analysis Strategy

- Generate time series and aggregated h-files for each survey
 - Use spans less than ~ 30 days to avoid biasing the position estimate from an incorrect velocity
 - Include cGPS data only on days when sGPS data are available to maintain common-mode cancellation
 - Strengthens the sGPS positions estimates within each survey and allows better assessment of the long-term statistics
 - Edit carefully the daily values within each span
- Generate time series and a velocity using the aggregated h-files from a span of 3 or more years
 - Edit carefully the long-term time series
 - Add 0.5 of white noise (`sig_neu`) to the cGPS estimates from each span to avoid overweighting the cGPS position estimates
 - Use a separate (ie.g PBO) analysis of the daily cGPS time series to get the appropriate RW (`mar_neu`) values for each cGPS site; use the median RW for the sGPS sites.
- See `sGPS_recipe.txt` for detailed commands

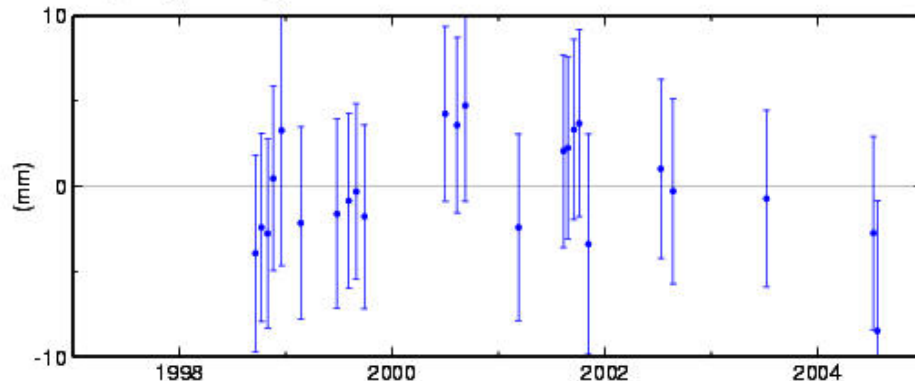
BURN North Offset 4762192.409 m
rate(mm/yr)= 0.88 ± 0.15 nrms= 0.59 wrms= 0.7 mm # 24



BURN East Offset 19785454.969 m
rate(mm/yr)= -2.20 ± 0.15 nrms= 0.96 wrms= 1.1 mm # 24



BURN Up Offset 1180.888 m
rate(mm/yr)= -2.11 ± 0.68 nrms= 0.54 wrms= 3.0 mm # 24

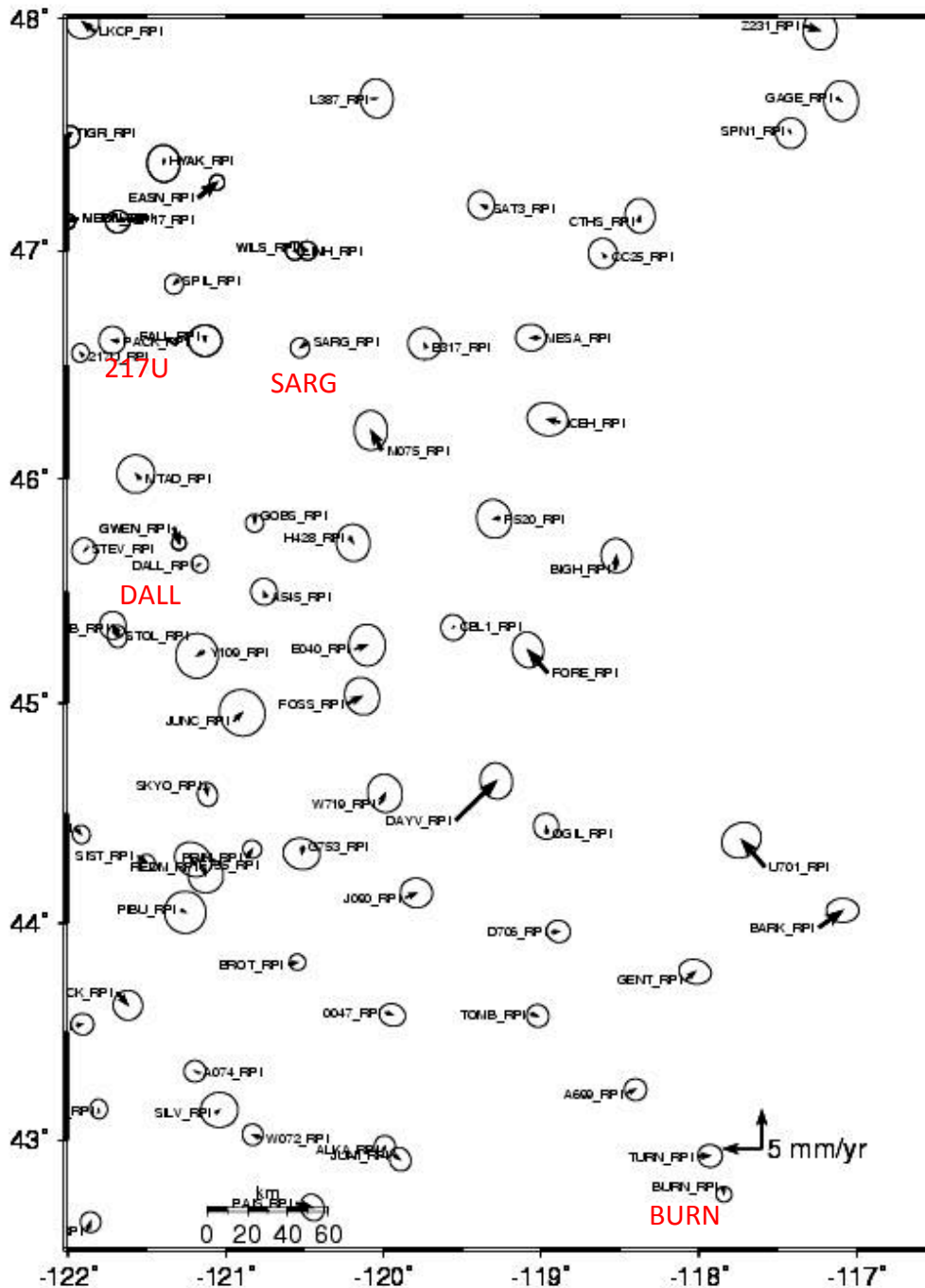


Time series of monthly position estimates for continuous site BURN

Wrms ~ 1 mm N,E
~ 3 mm U

Rate uncertainties
< 0.2 mm/yr N,E

0.7 mm/yr U
do not include random walk added for velocity estimates

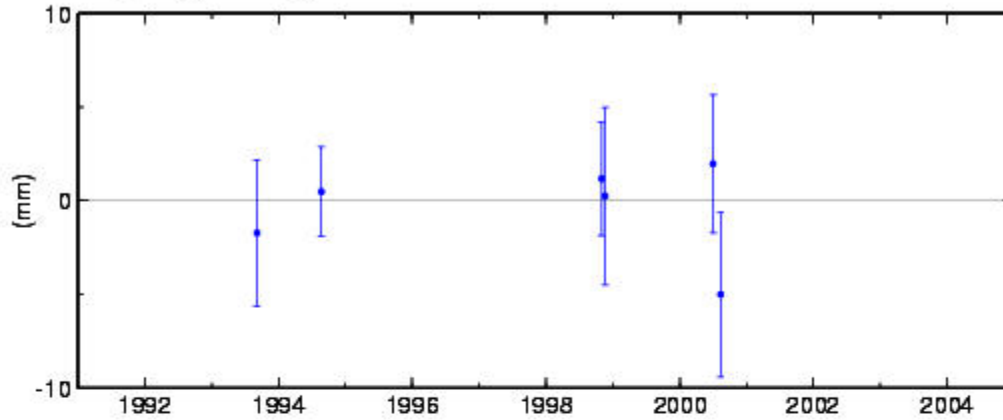


Next slide shows time series for survey-mode site 217U

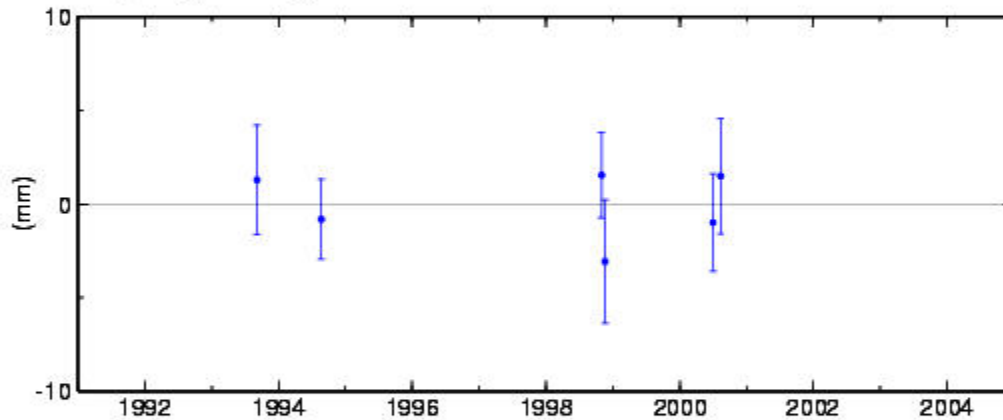
Note consistency with nearby sites

Time series for survey-mode site 217U

217U North Offset 5180993.436 m
rate(mm/yr)= 4.78 ± 0.51 nrms= 0.70 wrms= 2.4 mm # 6



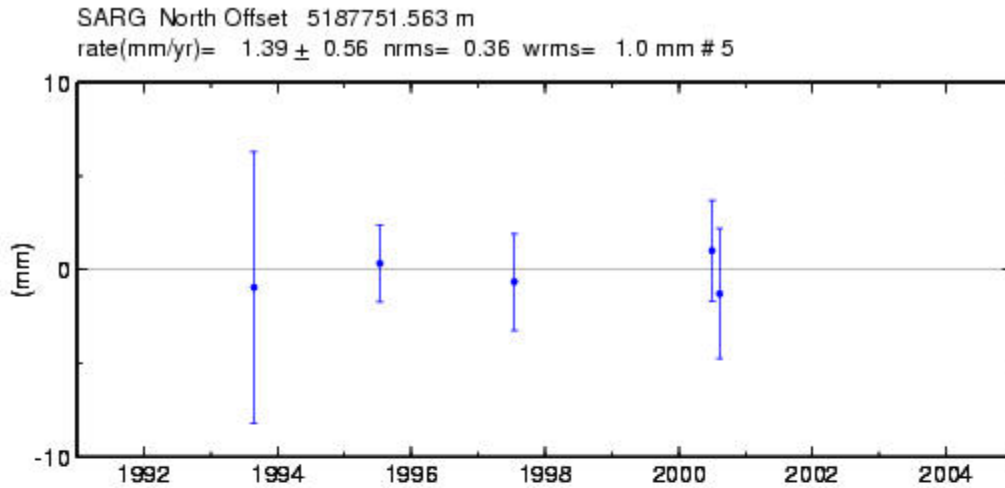
217U East Offset 18230721.379 m
rate(mm/yr)= 3.05 ± 0.39 nrms= 0.72 wrms= 1.9 mm # 6



Position estimates based on 8-24 hr occupations

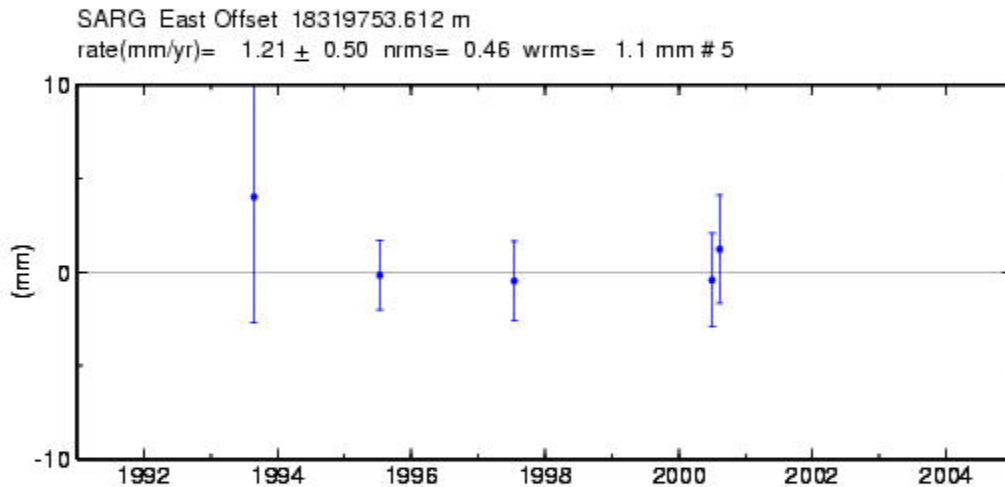
Note < 1 mm rate uncertainties due to 7-yr time span

Horizontal time series for survey-mode site SARG

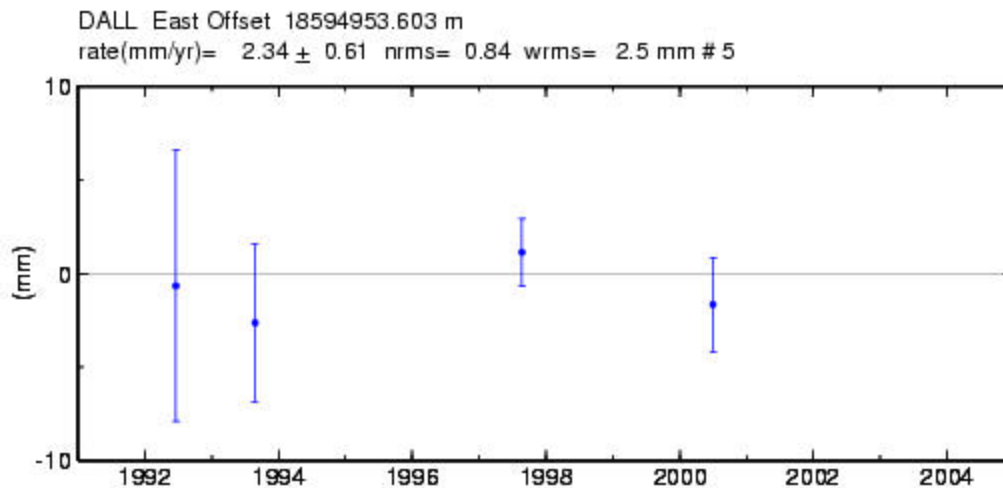
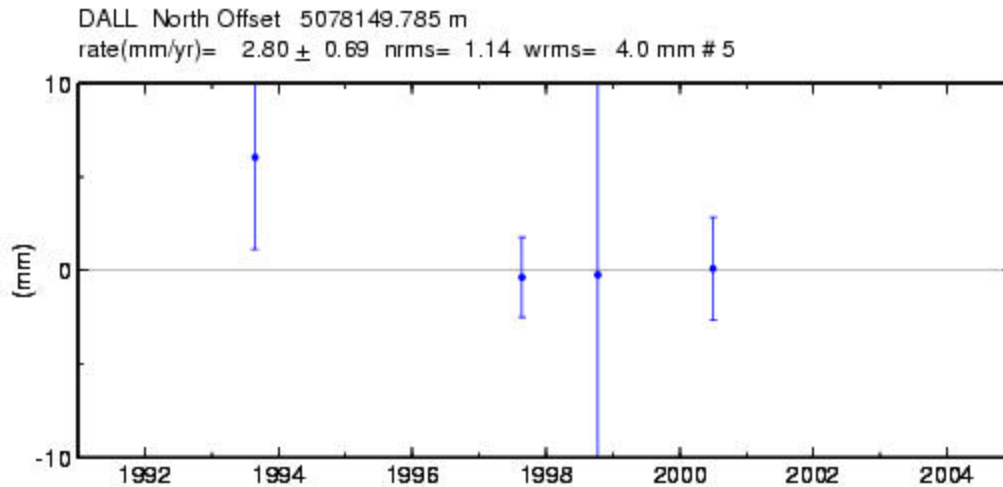


Position estimates
based on 8-24 hr
occupations

Note 1 mm wrms and
< 1 mm rate sigmas



Horizontal time series for survey-mode site DALL



Position estimates
based on 8-24 hr
occupations

Rate sigmas < 1 mm/yr
and consistent with
surrounding sites even
with velocities
determined essentially
by two occupations 3
yrs apart