



# Survey-mode measurements and analysis

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GPS Data Processing and Analysis with GAMIT/GLOBK and track

GNS Science, Lower Hutt, New Zealand

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[http://geoweb.mit.edu/~floyd/courses/gg/201802\\_GNS/](http://geoweb.mit.edu/~floyd/courses/gg/201802_GNS/)

Material from R. W. King, T. A. Herring, M. A. Floyd (MIT) and S. C. McClusky (now at ANU)

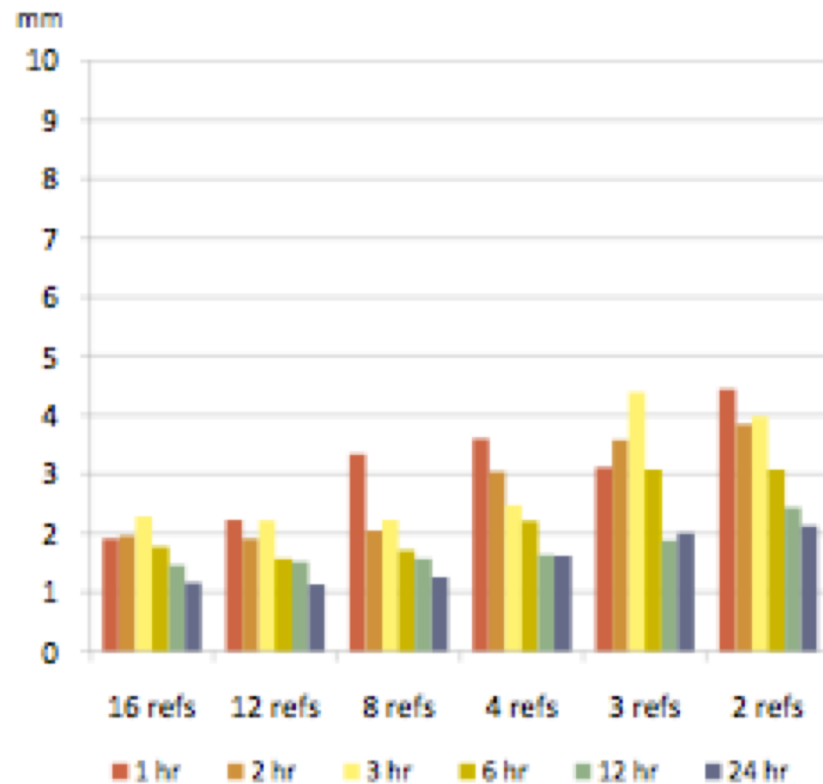
# Measurement strategies I

## Occupation time

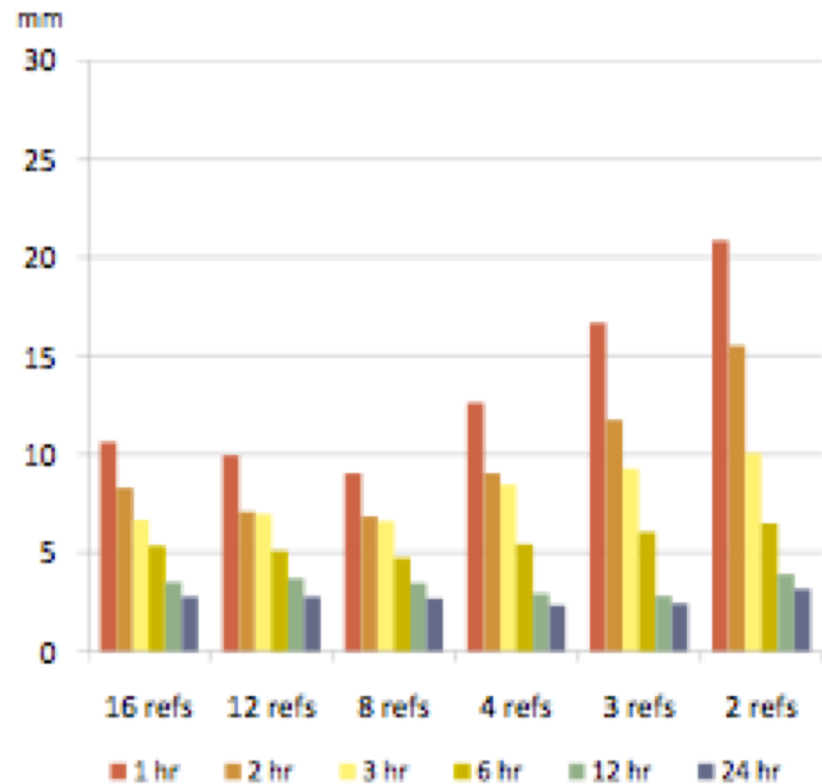
- Given time and personnel constraints, what are the trade-offs between between spatial and temporal density?
- Ideally, you would like for the white noise position uncertainty for an occupation to contribute to the velocity uncertainty at a level less than the usually dominant long-period correlated noise
- Typical white noise uncertainties (horizontal and vertical) as a function of occupation time are:
  - 6–8 hrs: 2–2.5 mm (H), 5–10 mm (V)
  - 12–24 hrs: 1.0–1.5 mm (H), 3–5 mm (V)
  - 36–48-hrs: 0.7–1.0 mm (H), 2–4 mm (V)
- Observations over 3 or more days will give you more redundancy
- Observations of 5 or more days will be necessary for mm-level vertical uncertainties
- If your region has few continuous stations, you should consider running one or two survey-mode stations for the entire time of the survey to provide continuity

# Precision v session length for network processing

horizontal repeatability



vertical repeatability



# Measurement strategies II

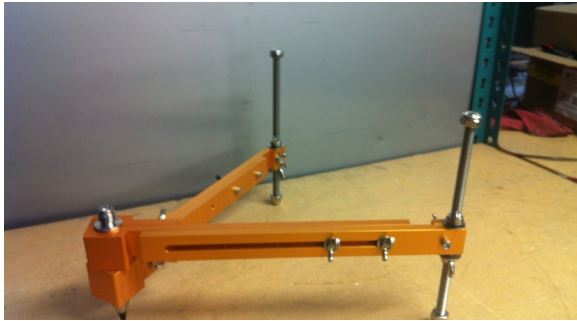
## Monuments and instrumentation

- Issues in site and antenna selection:
  - Monument identification
  - Monument stability
  - Accessibility
  - Ease of setup
  - Multipath
  - Log (metadata) errors
  - Vandalism
- There is no clear prescription for all cases

Let's look at some examples...



# Three primary mounting options



Spike mount



Tripod with optical or physical plummet



Site VELA in the Soloman Islands.



Tech 2000 kit.

Mast

Survey-mode measurements and analysis

Courtesy UNAVO web page

# Surveyor's tripod

- Advantages:
  - Easily portable
  - Stable on flat ground
- Disadvantages:
  - Inconsistent height setup (variable multipath)
  - Easily disturbed



<http://facility.unavco.org>

# Fixed-height mast (e.g. Tech2000)

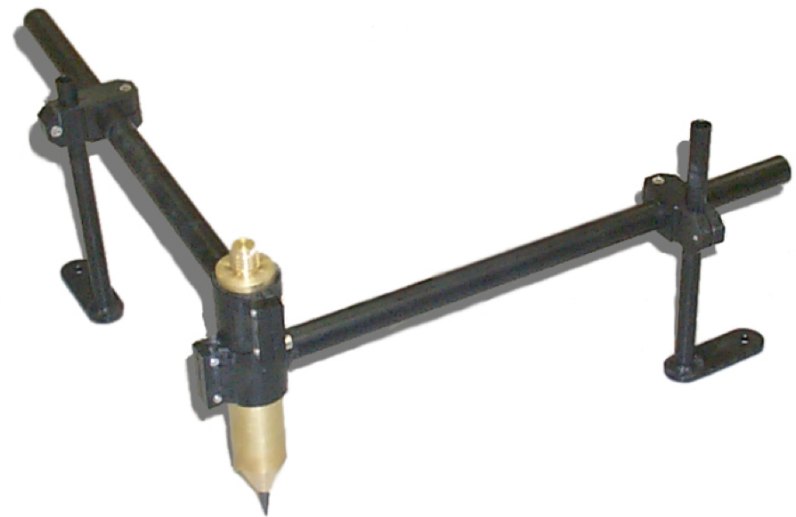
- Advantages:
  - Automatically centered
  - Fixed height (reduces human error)
  - Stable
  - Identical multipath environment each setup
- Disadvantages:
  - Difficult first-time placement due to anchor installation (also requires large, hard surface)



<http://facility.unavco.org>

# Spike mounts

- Advantages:
  - Fixed height
  - Low height reduces horizontal centering inaccuracy if slightly off level
  - Easily hidden from vandals
- Disadvantages:
  - Awkward to level precisely and orientate antenna
  - Proximity to ground may increase direct multipath signal



<http://facility.unavco.org>



# Examples of survey marks



Cast pl



ete pillars



Glued punched coin



Driven rods



Drilled pin



# Site identification errors



Photograph by M. Floyd

Photograph by M. Floyd

Photograph by M. Floyd



# Antenna setup errors

- Episodic survey setups can mean that measurements are not centered perfectly over a mark or the antenna height not measured accurately
- These measurements tend to exhibit an independent and random nature



# Log (metadata) and archive errors

Critical: antenna type (serial #);  
height and type; monument id

```

2.10      OBSERVATION DATA      G (GPS)      RINEX VER
teqc 2006Jul20      UNAVCO Archive Ops      20060725 16:48:29UTC PGM / RU
Solaris 5.9|UltraSparc Iii|cc -xarch=v9 SC5.5|+|-|*Sparc      COMMENT
BIT 2 OF LLI FLAGS DATA COLLECTED UNDER A/S CONDITION      COMMENT
U626      MARKER NA
U626      MARKER NA
UNKNOWN      Stanford University      OBSERVER
3414A05687      TRIMBLE 4000SSE      NP 5.71 / SP 1.26      REC # /
3015A00136      TRM14532.00      ANT # /
-2683218.2014 -4185018.7102 3983204.9361      APPROX P
1.4755      0.0000      0.0000      ANTENNA:
1      1      WAVELENG
5      L1      L2      C1      P1      P2      # / TYPE
30.0000      INTERVAL

1994      9      28      16      7      30.0000000      GPS      TIME OF
END OF H

94 9 28 16 7 30.0000000 0 5G 5G 6G17G20G24
2437477.48856      1792564.39355      22428902.4774      22
-548226.77657      -402556.82256      20834866.1484      20
-567509.56556      -371824.37155      22860949.9614      22
1203057.74657      883752.12057      20612879.2734      20
793138.12755      501650.82355      22928979.6334      22
    
```

L03662801 36028

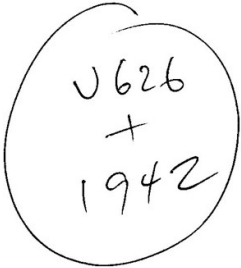
### GPS Daily Observation Log

Stanford University Session Name: U626-271-0

Station Name: <u>U626</u>	4-Char ID: <u>U626</u>
Location: <u>Geysers</u>	California
Observing Monument Inscription: <u>U626-1942</u>	

Operators: <u>Carl Chap</u>	Receiver: <u>Trimble 4000</u>
Agency: <u>Stanford U.</u>	Serial #: _____
	Antenna: " _____ "
	Serial #: <u>000140</u> Cable Length: <u>5</u>
<b>PROGRAMMING</b>	
Elevation Mask: <u>10°</u>	
Collection Rate: <u>30°</u>	
Notes: _____	

Sketch of Observing Monument



Antenna Height Above Mark in Meters			
Slant	<input checked="" type="checkbox"/>	or Vertical	<input type="checkbox"/>
Notch #	Before	After	
1	<u>115.6m</u>	<u>115.6</u>	
2	<u>115.5m</u>	<u>115.5</u>	
3	<u>115.6m</u>	<u>115.6</u>	
Average:	<u>115.56</u>	<u>115.56</u>	
Ht. in Inches:	<u>45 3/4"</u>	<u>45 1/4"</u>	
Height Entered into Receiver:	<u>115.56m</u>		
Magnetic Declination:	<u>34.6°</u>		
Compass Reading:	_____		

Observation Times	UTC Time	UTC Date	UTC Day	Local Time	Local Date
Scheduled Start Time:	_____	_____	_____	_____	_____
Scheduled End Time:	_____	_____	_____	_____	_____
Actual Start Time:	<u>16:07</u>	<u>271</u>	<u>271</u>	<u>9:07 AM</u>	<u>9/28/94</u>
Actual End Time:	<u>23:26</u>	<u>9/28</u>	<u>271</u>	<u>4:26 PM</u>	<u>9/28/94</u>
Daily Session Number:	_____	Session Name in Receiver:	<u>271-0</u>		

Did anything abnormal or unusual occur?  Yes  No. Discuss any significant Problems.

END  
Bubble Division high to South  
← TRM

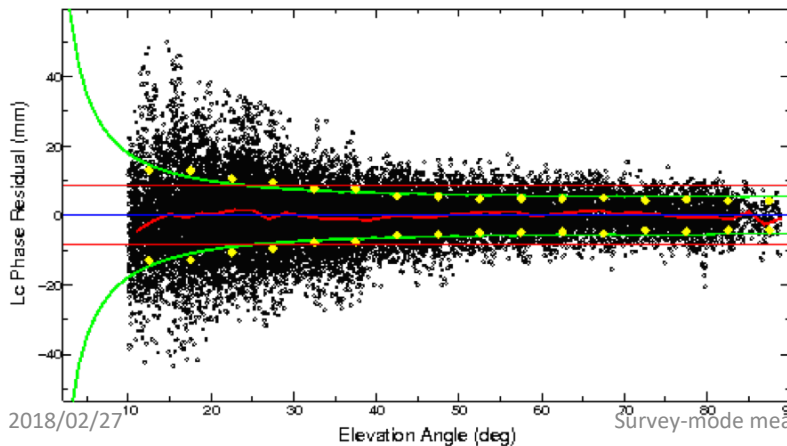


# Low mount in a good environment



STVP  
Steven's Pass, Cascades  
Range in western  
Washington

18-cm spike mount

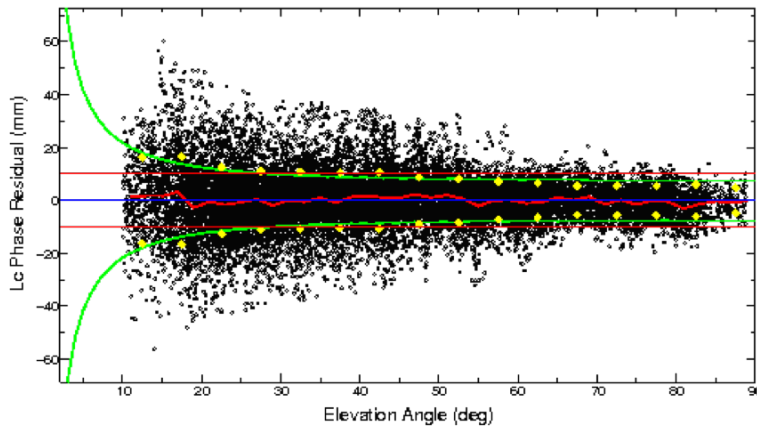


No long-term repeatability yet, but 44 hrs of observations in 2012 give formal uncertainties 0.5 mm horizontal, 3 mm vertical. Note minimal long-period signal scattering.

# Low mount in a dirty environment



B059  
Roadside  
meadow in  
western  
Washington  
12.5-cm spike  
mount



Two 24-hr measurements in 2012 agree at 1 mm horizontal, 4 mm vertical though the formal uncertainties are 2 mm, 10mm due to high random noise (diffuse multipath or water vapor?) Note minimal long-period signal scattering. Long-term scatter is 3 mm horizontal, 5 mm vertical (monument instability?)

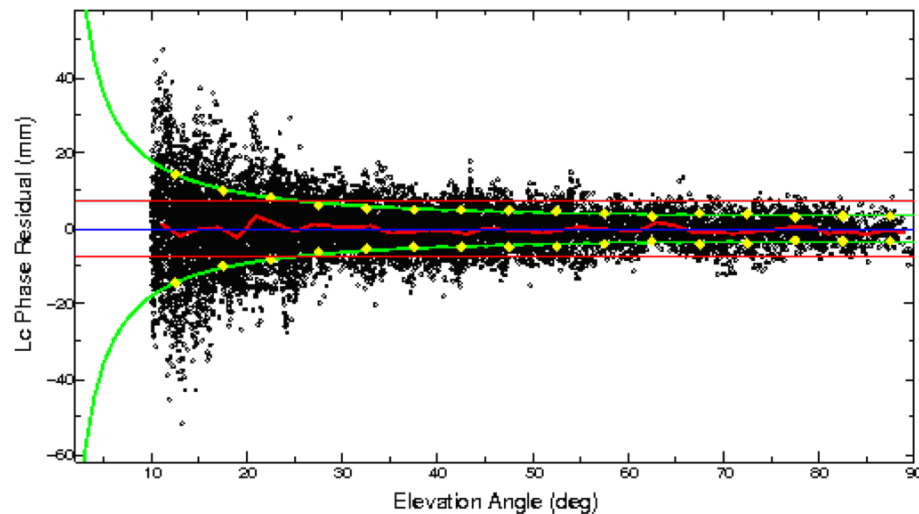


# High mount in a dirty environment



C033

Old survey mark in dirt in central Washington. Tripod mount. (Train blockage was short-lived)

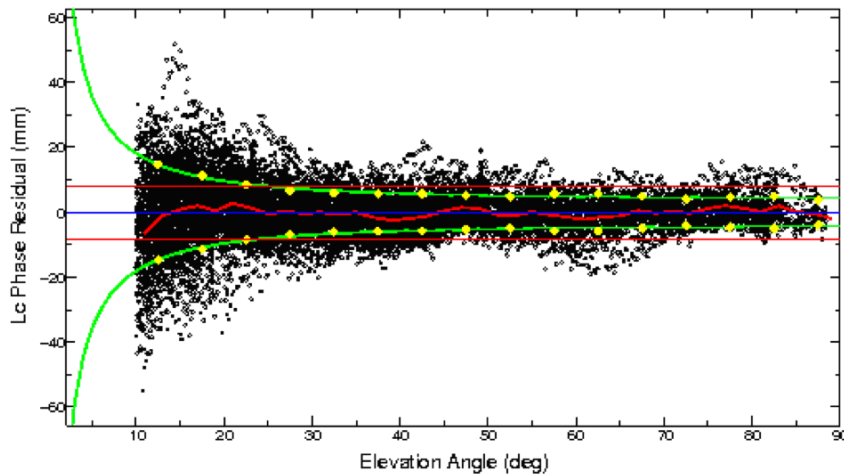


2012 19-hr session and 5-hr session agree at 1.5 mm horizontal, 3 mm vertical. Long-term repeatability 2 mm horizontal, 12 mm vertical.

Surprisingly little short-period multipath (dry dirt?)

# Low mount on a slope

LYFR  
Rocky river bank  
in eastern  
Oregon  
12.5-cm spike  
mount



Single 14-hr session . Long-  
period multipath due to slope  
and/or reflective rocks ?

# Special characteristics of survey-mode data

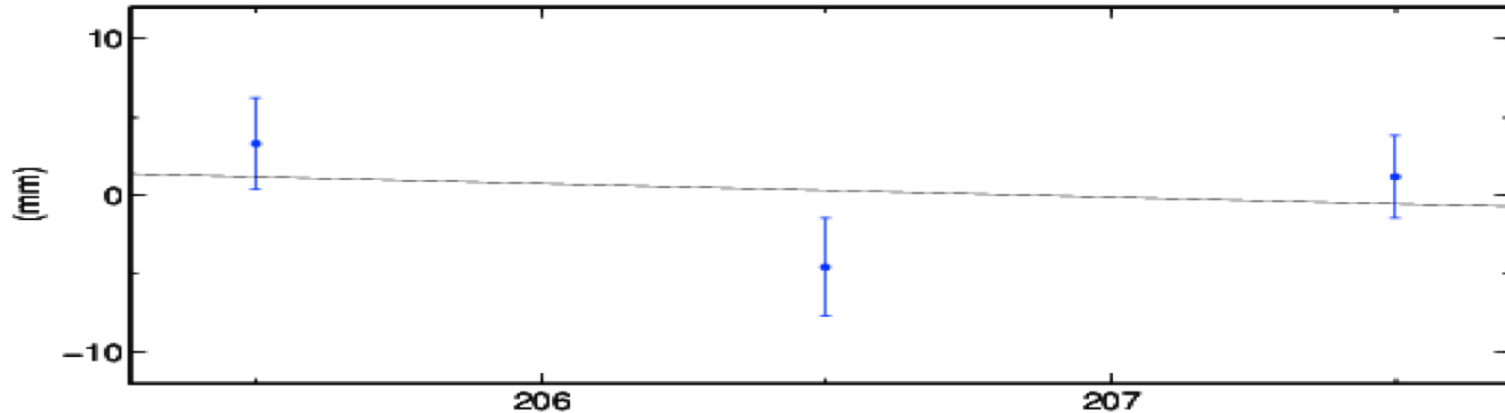
- Editing is critical: every point counts
- Usually combined with cGNSS data to provide continuity and a tie to the ITRF
- Appropriate relative weighting needed in combining with cGNSS data
- Antenna meta-data may be more complicated
- Heights may be problematic if different antennas used
- Seasonal errors behave differently than in cGNSS data: best strategy is to observe at the same time of the year (unlike cGNSS, which has minimal seasonal sensitivity at 1.5, 2.5, 3.5 ...years total span)

# Analysis strategy

- Generate time series and aggregated h-files for each survey
  - Use spans less than  $\sim 20$  days to avoid biasing the position estimate from an incorrect a priori velocity
  - Include cGNSS data only on days when sGNSS data are available to maintain common-mode cancellation
  - Aggregation of sGNSS positions estimate within each survey to allow better assessment of the long-term statistics
  - Edit carefully the daily values within each span
- Generate time series and a velocity using the aggregated h-files from a span of 3 or more years
  - Edit carefully the long-term time series
  - Add 0.5 of white noise (“sig\_neu”) to the cGNSS estimates from each span to avoid overweighting the cGPS position estimates
  - Use a separate (e.g. PBO) analysis of the daily cGNSS time series to get the appropriate RW (“mar\_neu”) values for each cGNSS site, then use the median RW for the sGNSS sites
- See sGPS\_recipe.txt for detailed commands

# Editing example

RFHY\_GAO North Offset 4443176.449 m  
rate(mm/yr) =  $-312.11 \pm 716.58$  nrms = 1.84 wrms = 5.3 mm # 3



RFHY\_GAO East Offset 3310588.142 m  
rate(mm/yr) =  $-287.09 \pm 560.34$  nrms = 2.71 wrms = 6.1 mm # 3

