

Examples of track use

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Material from R. King, T. Herring, M. Floyd (MIT) and S. McClusky (now ANU)

Outline

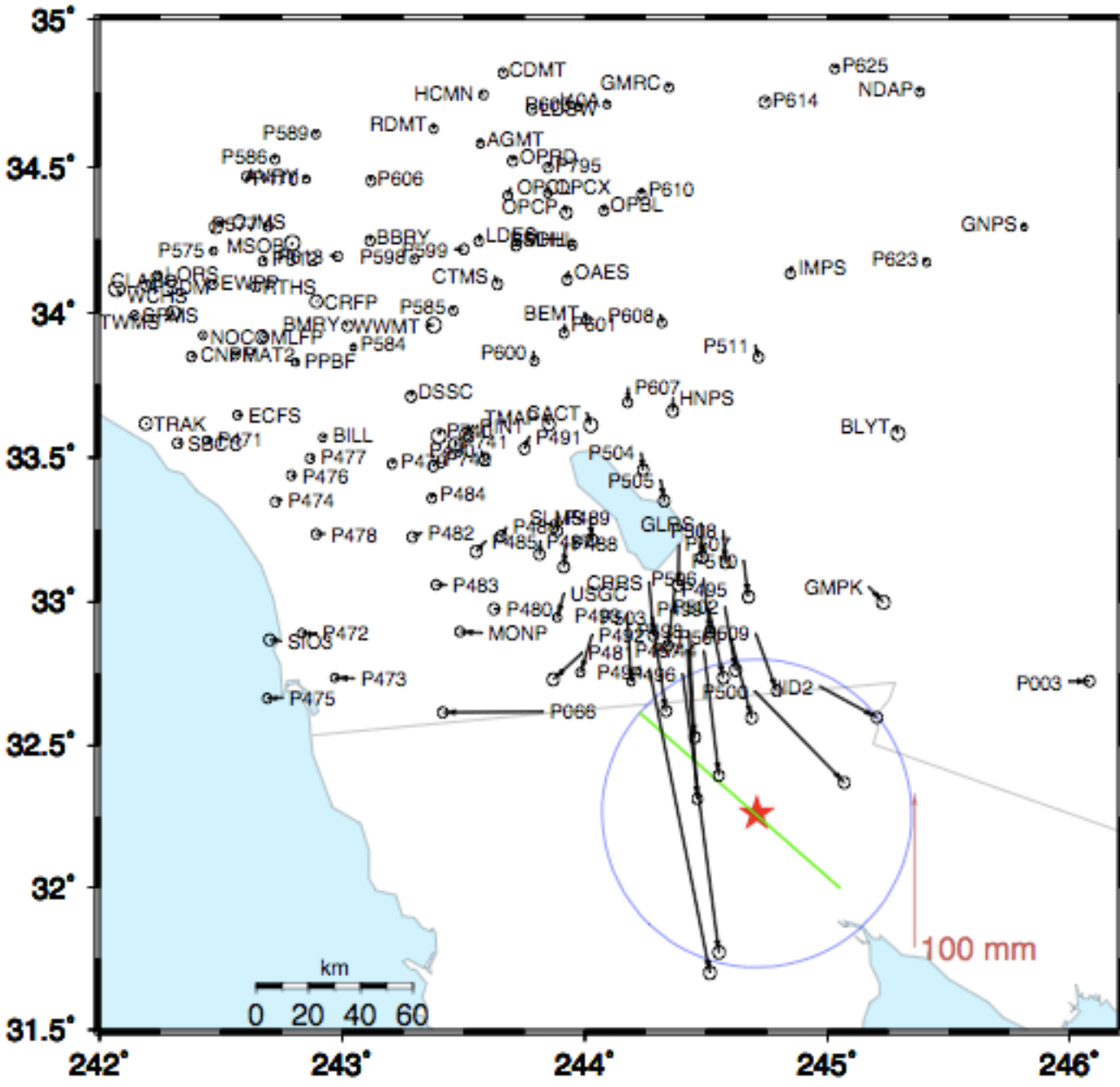
- Kinematic examples
 1. GPS seismology
 2. Roving GPS
 3. Rapid deformation
- Static examples
 4. Short-static occupations
 5. Deciphering interference
- Remember the rule-of-thumb for proportional errors:

$$\epsilon_{BL} \sim \epsilon_{SV} \times BL/h_{SV}$$

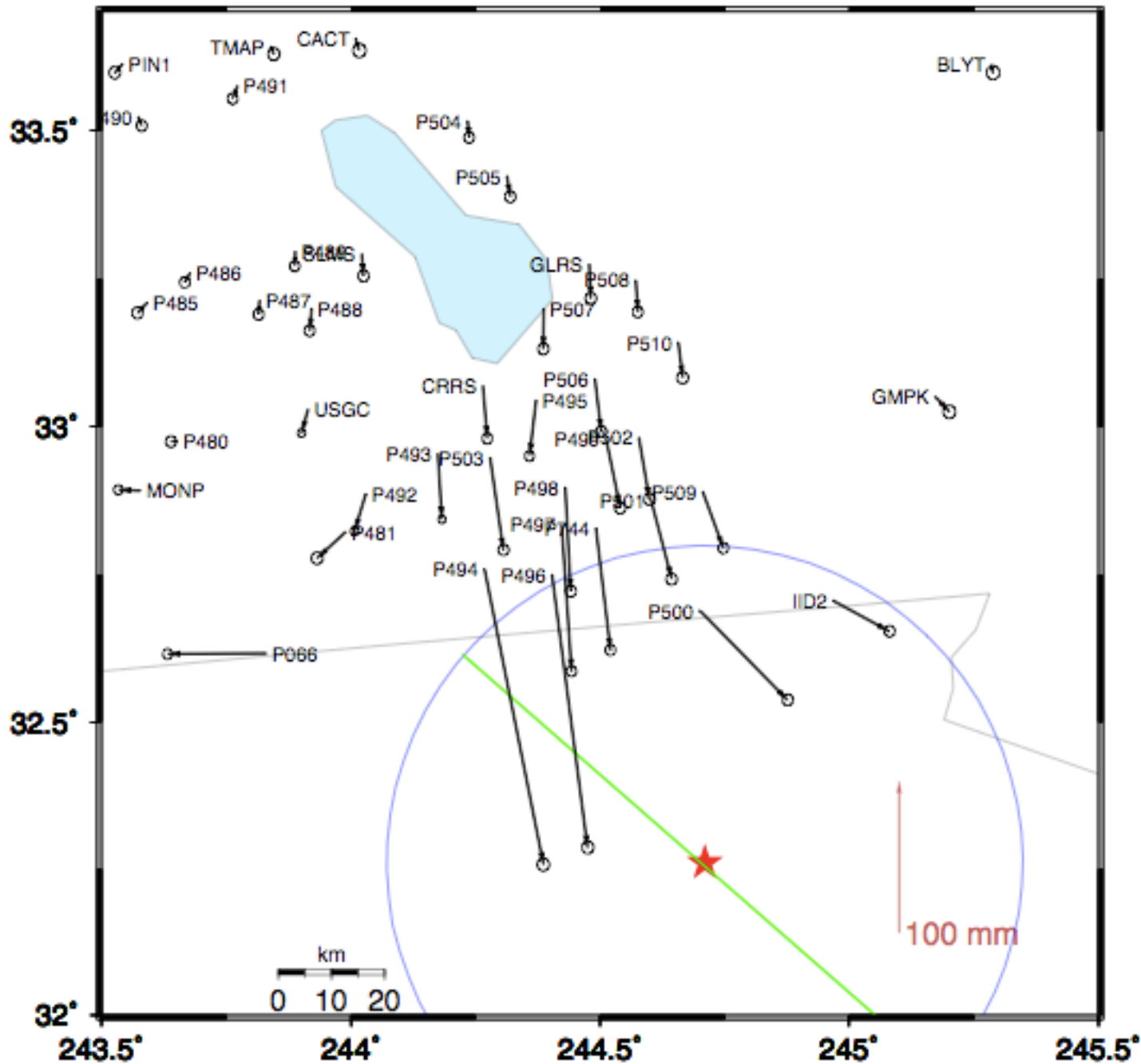
Example 1: GPS seismology

- Examine the short baseline MIT results: Look at this example in more detail later
- April 4, 2010 El-Mayor Cucapah earthquake in Baja California: 5-Hz results. Look later at long baseline processing for these sites.
- Track results are generated in two steps:
 - First solution uses zero process noise except during time of earthquake (long baseline solution)
 - Final results generated with fixed ambiguities from first solution read in (-a option).
 - Long baseline ambiguity resolution with stochastic site coordinates needs LC estimate which can be noisy due to stochasticity.

Coseismic offsets



- Offsets based on 2-days before and after earthquake.
- Two days used is reduce leakage of postseismic motions.
- Red Star is epicenter; blue circle is 60 km (15-20 seconds surface wave speed)



Zoom around border

Sites near the epicenter.

Blue circle is 60 km radius Displacement s

P494 200 mm

P496 182 mm

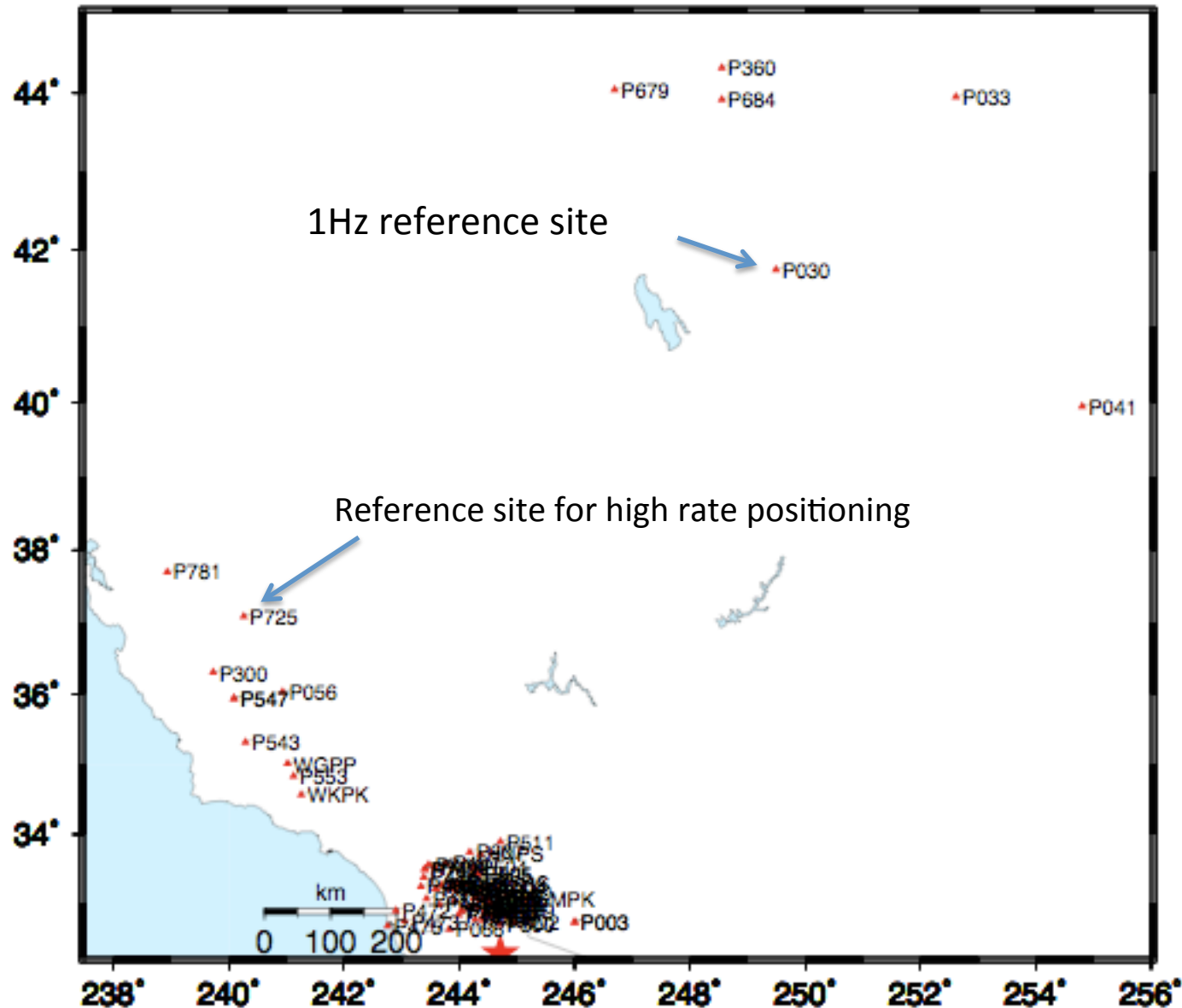
P497 97 mm

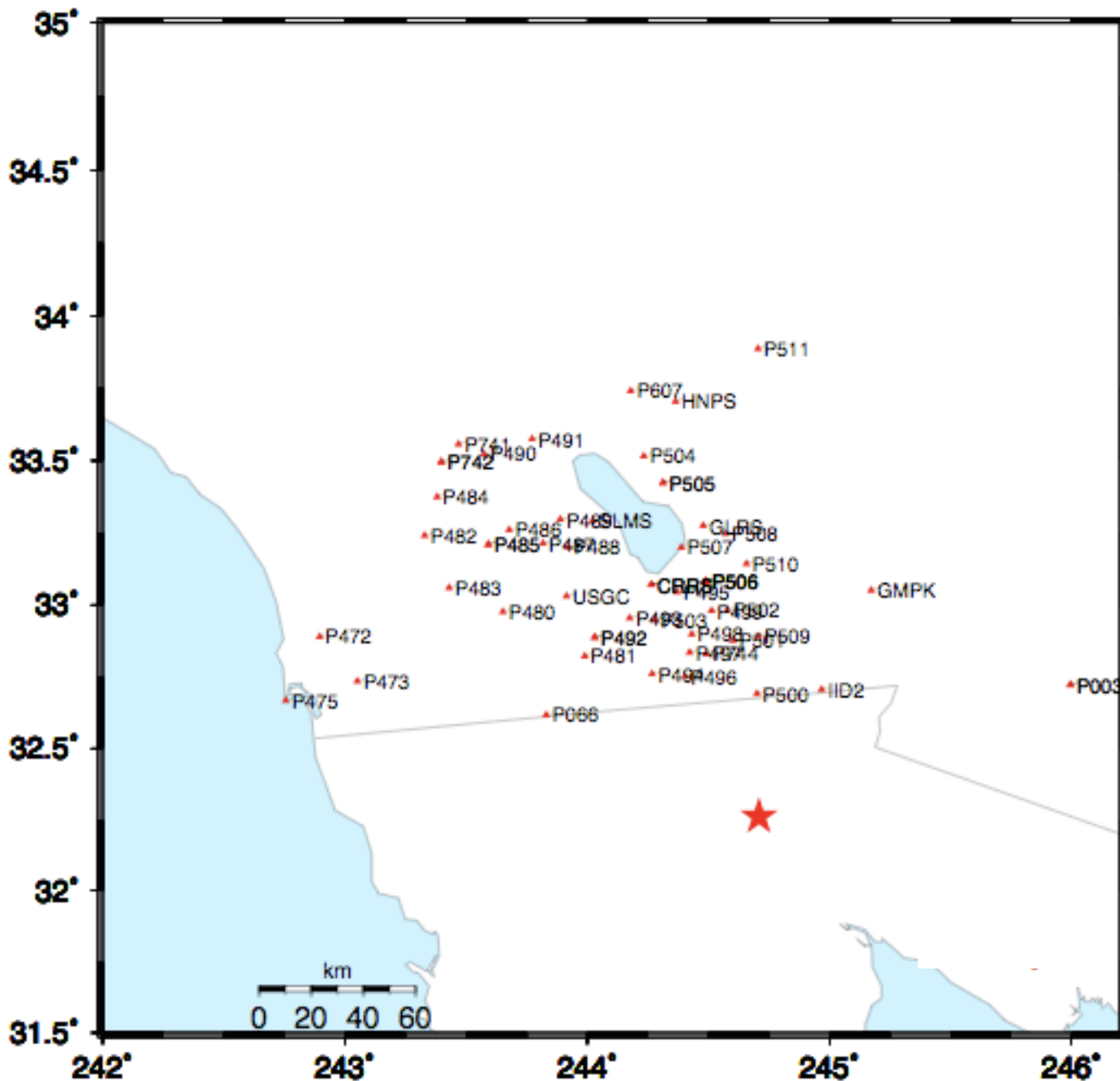
...

P491 9 mm

High-rate GPS site download

- High rate data from these sites downloaded after event.
- Most sites are 5-Hz; more distant sites are 1-Hz.

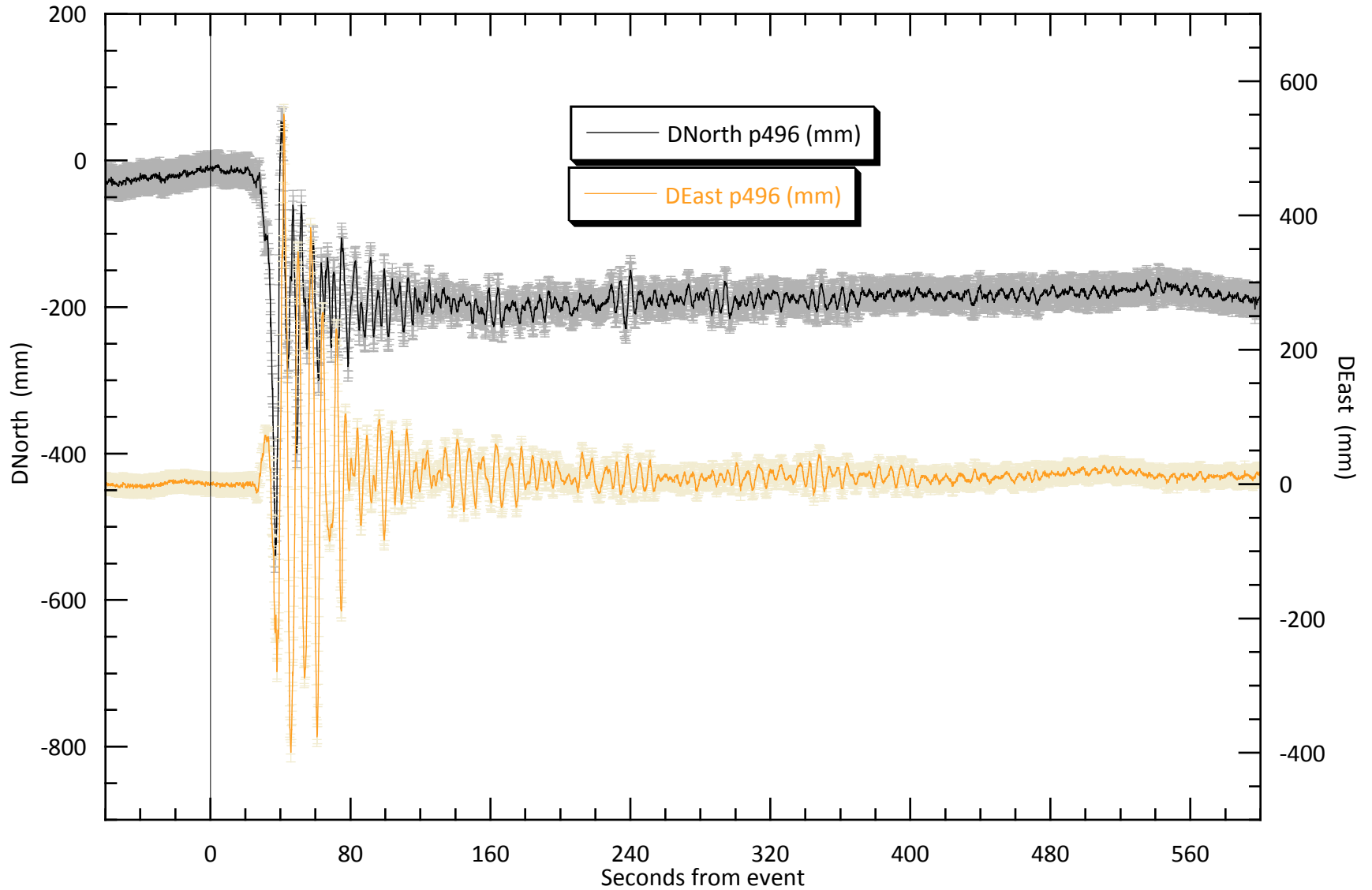




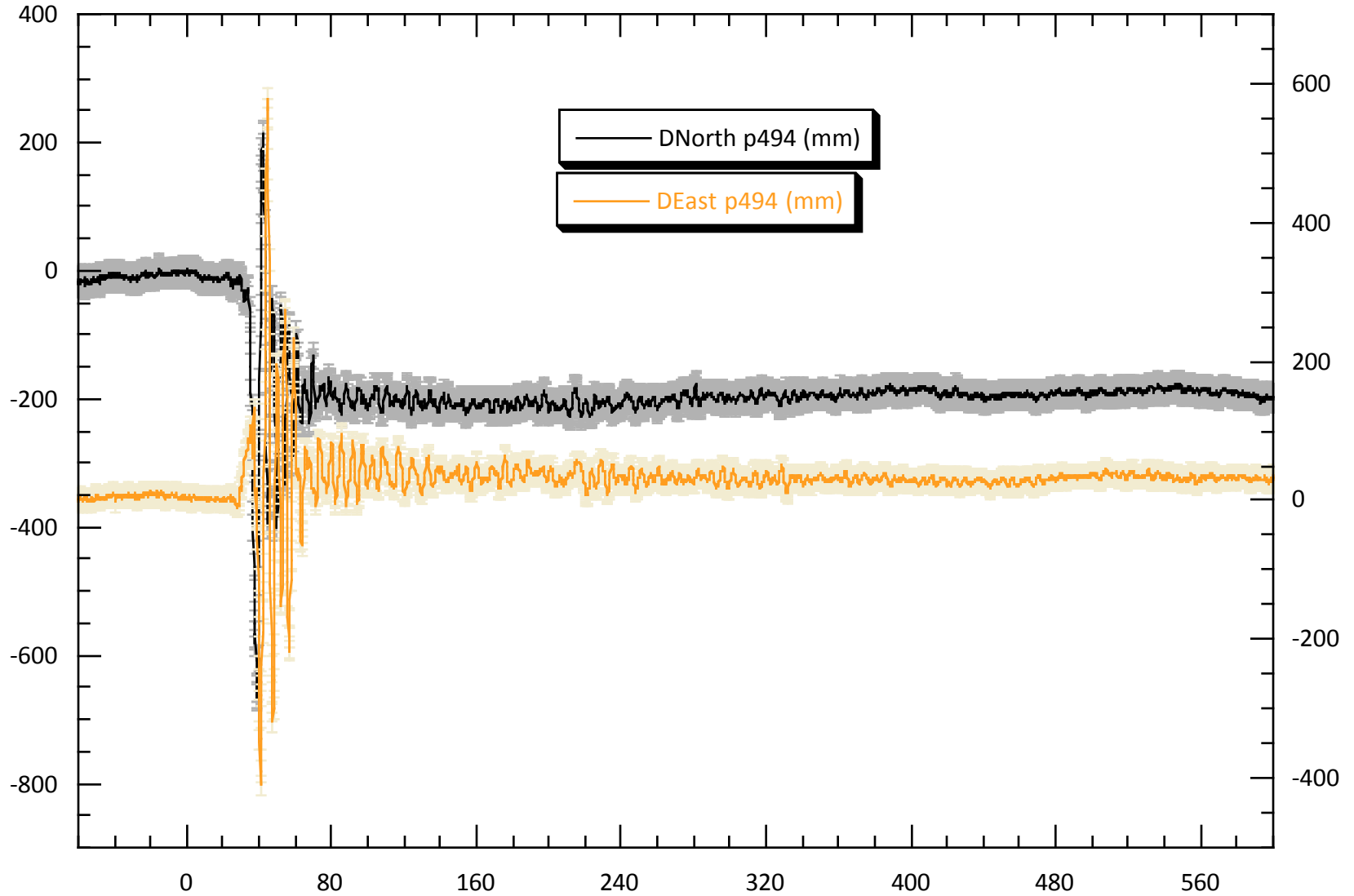
Sites in coseismic region

- Sites shown have 5-Hz data for 3-days before and after the earthquake
- Examine sequence of sites along US/Mexico border and North

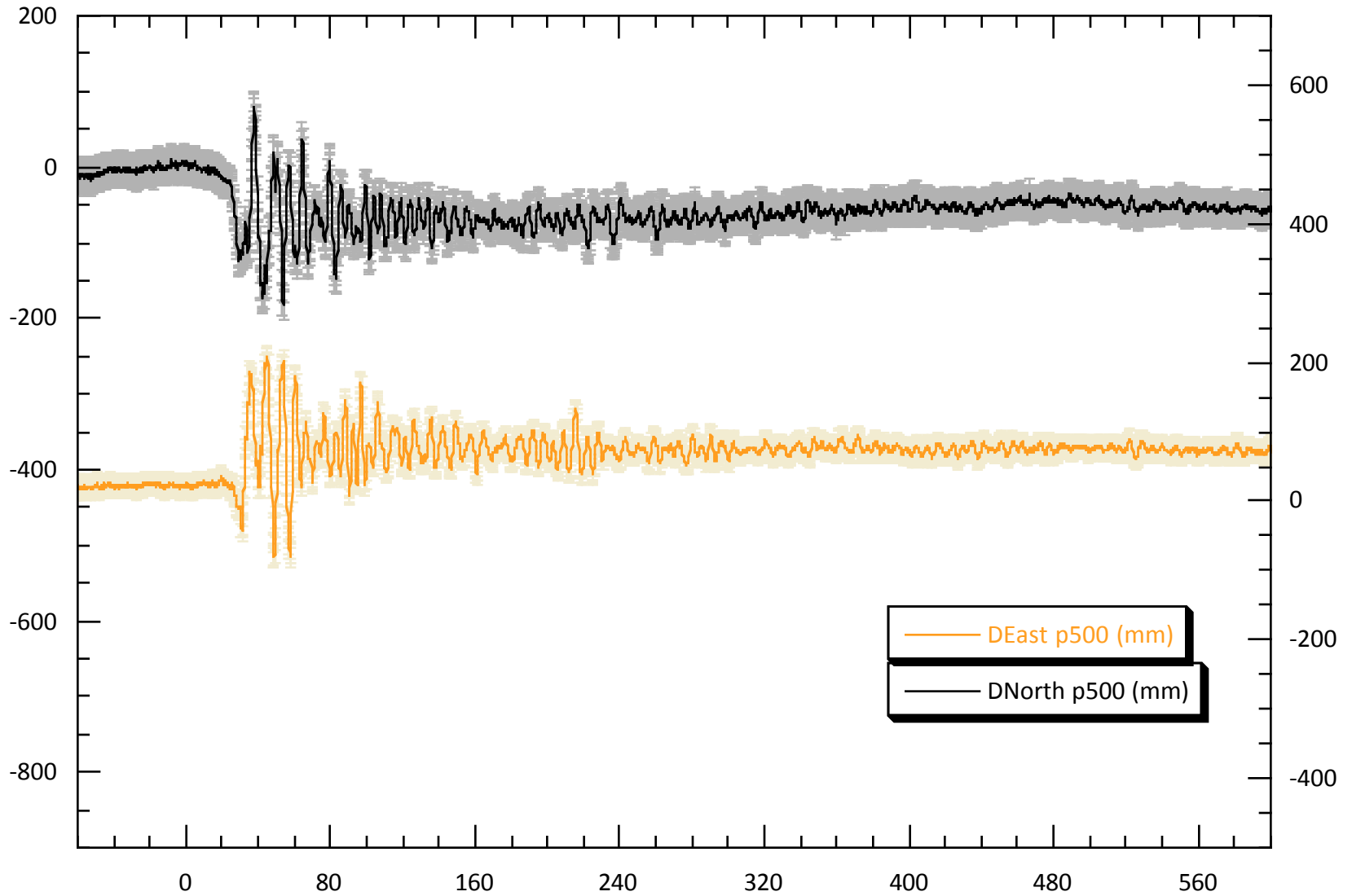
P496



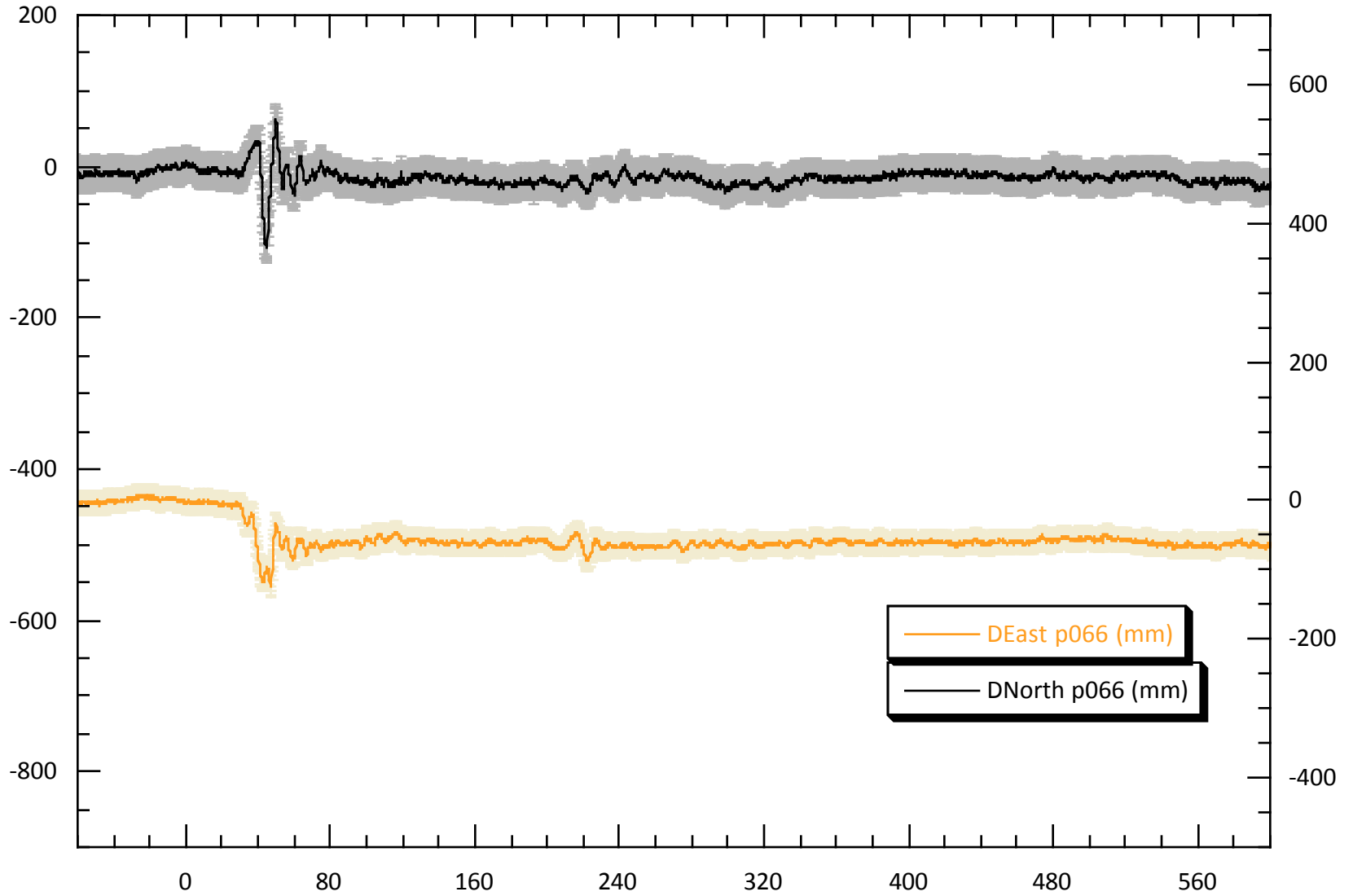
P494



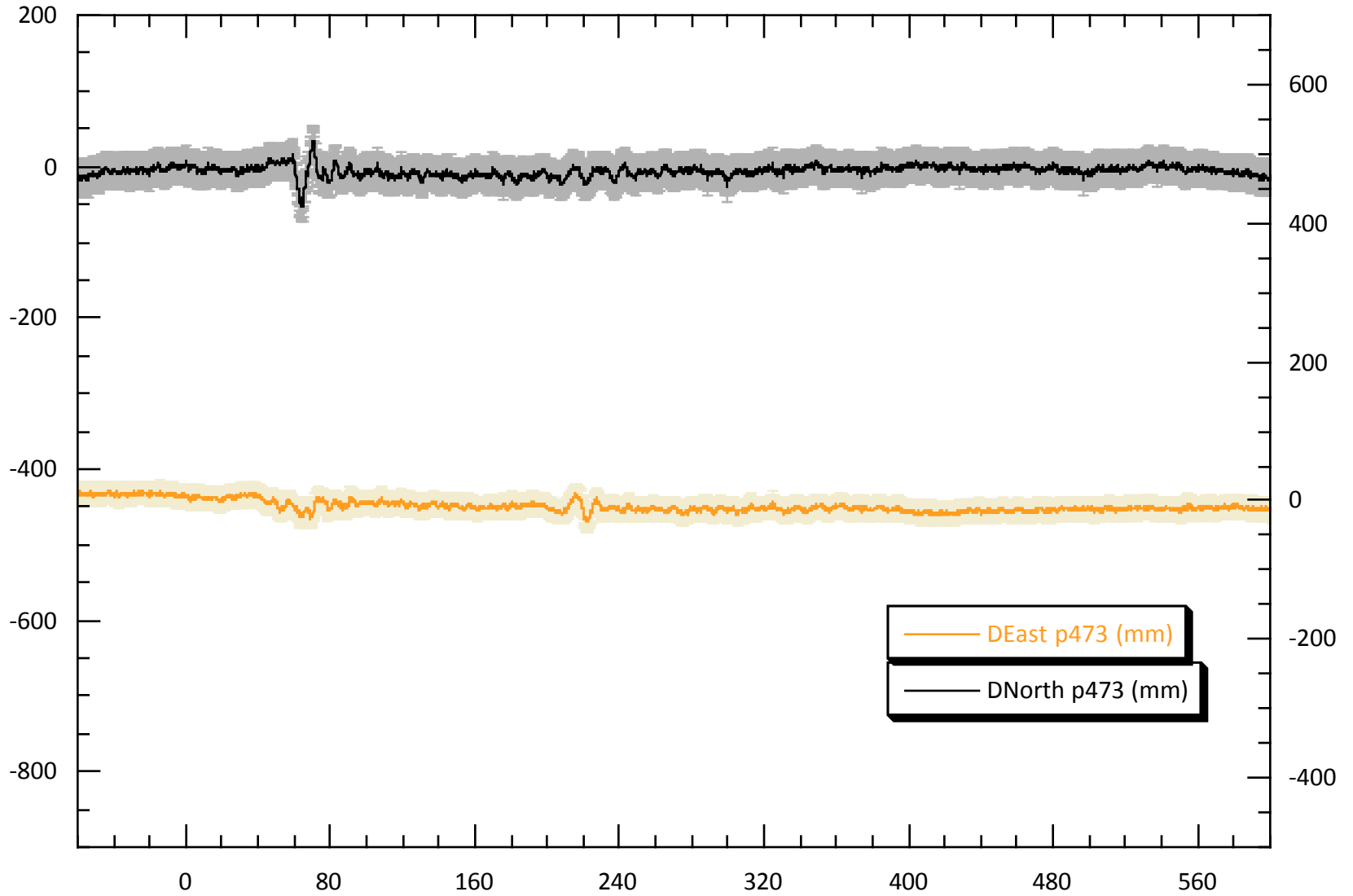
P500



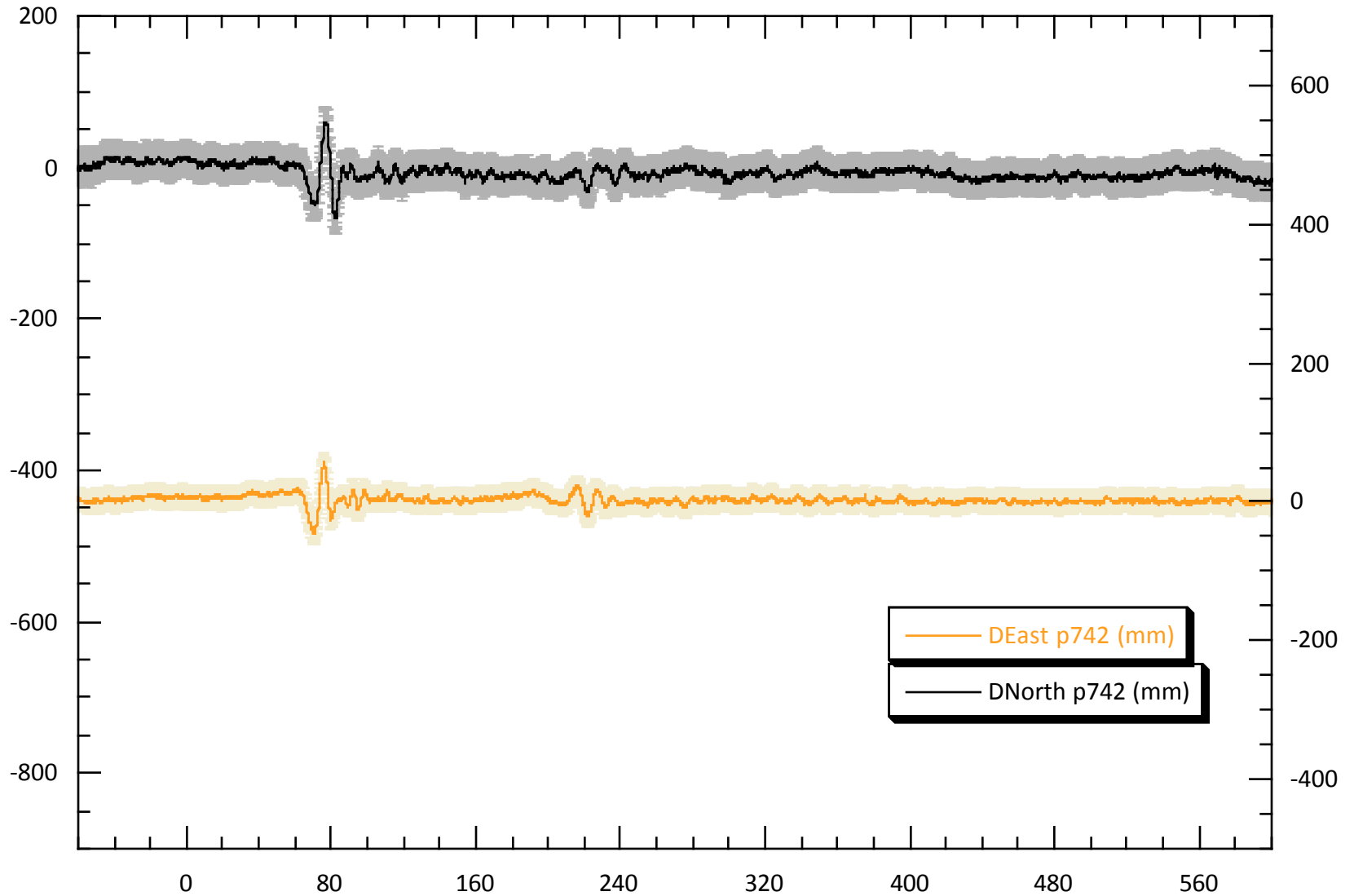
P066



P473

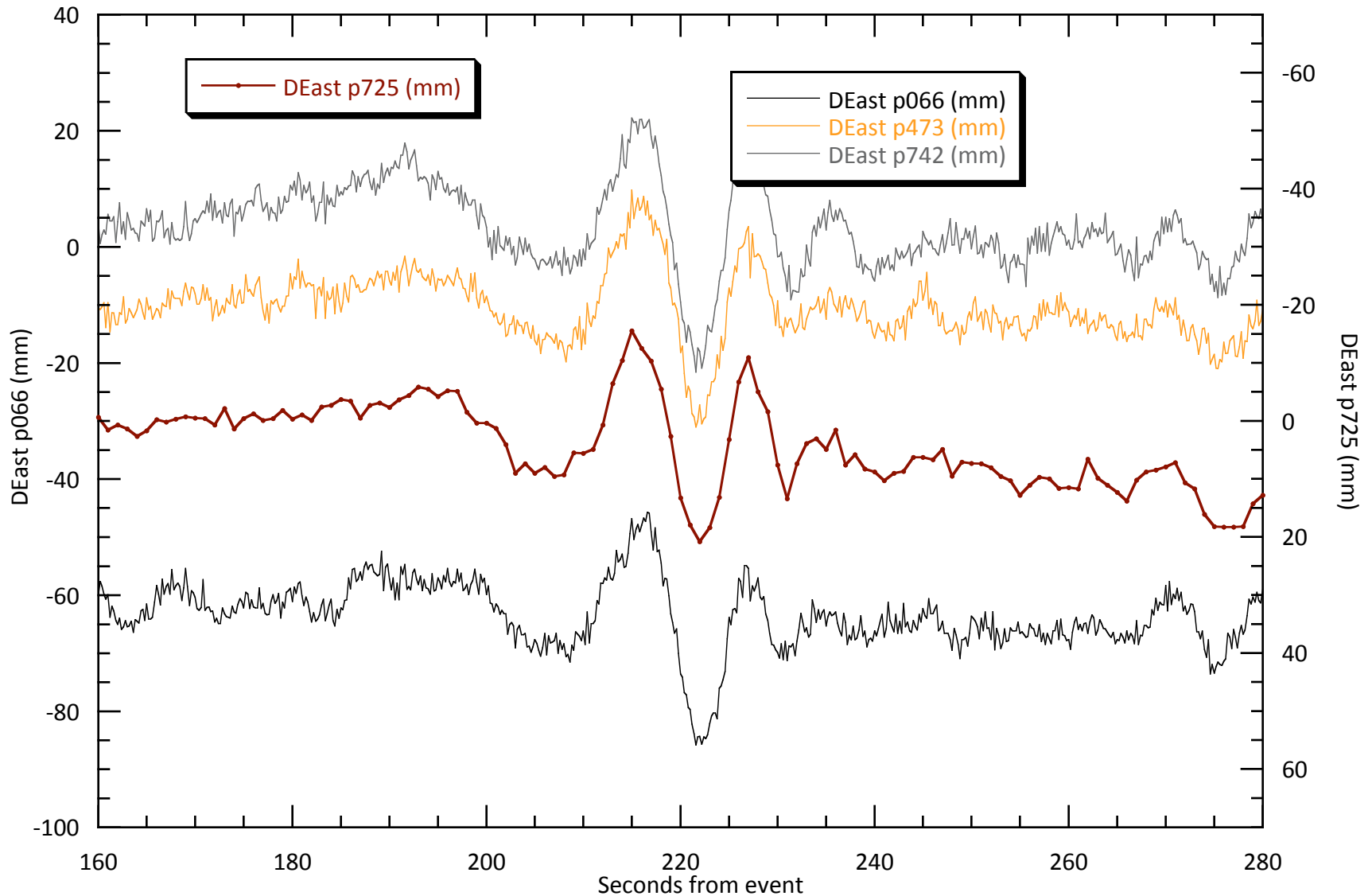


P742



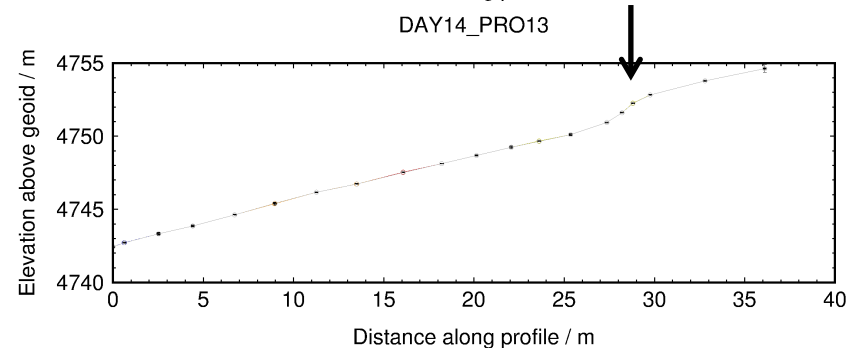
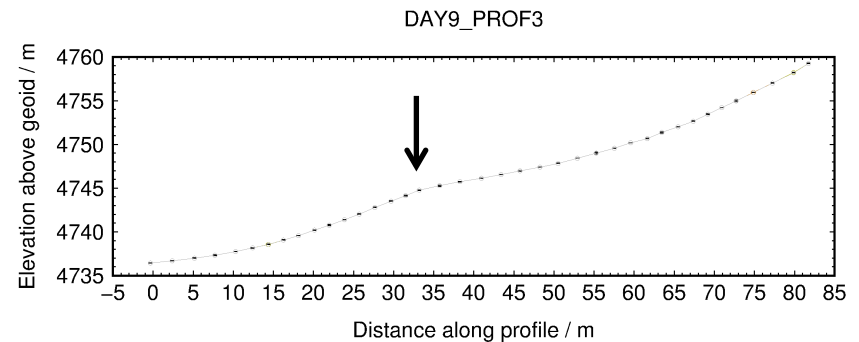
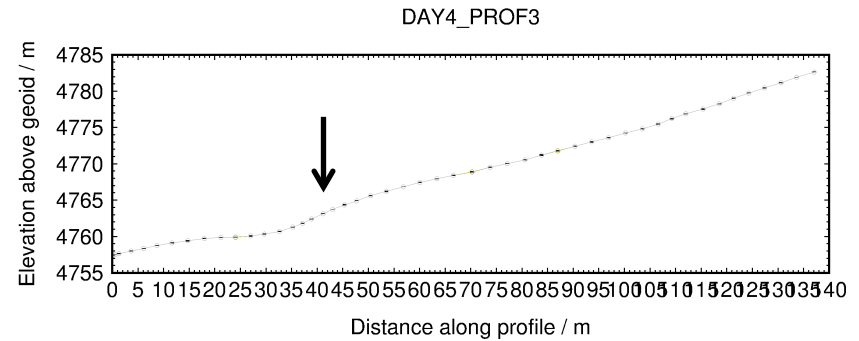
Surface wave arrival at P725

- P725 is ~600 km from epicenter. This signal common to sites is the arrival at the “reference site”



Example 2: Roving GPS

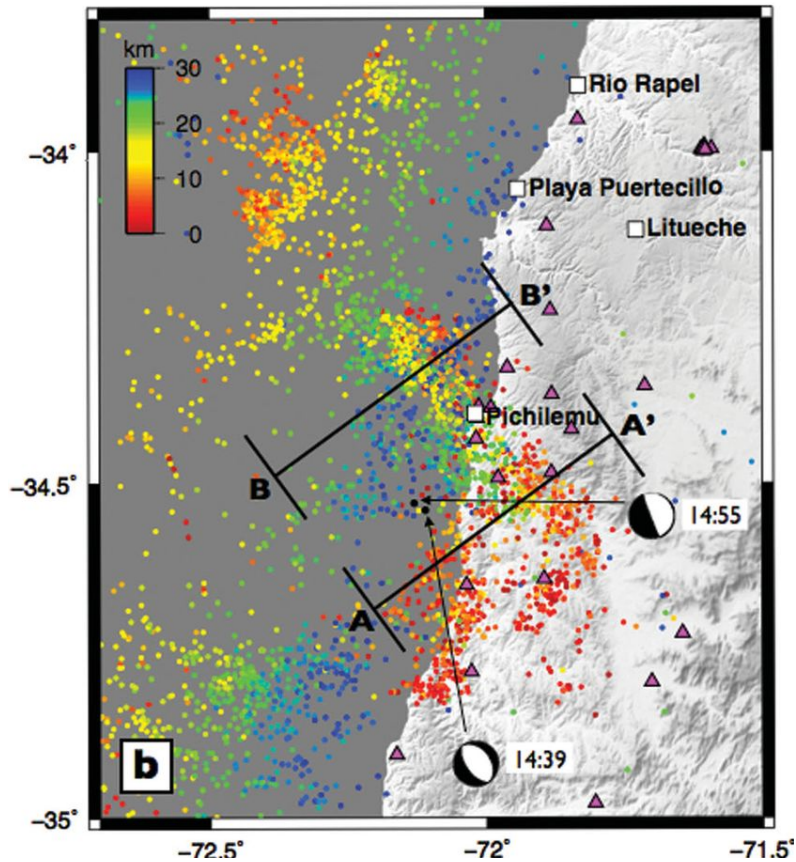
(from England et al., 2013)



Disclaimer: This example was *not* processed using TRACK because the kinematic equipment was single-frequency, i.e. L1-only, and TRACK requires dual-frequency data

Example 3: Rapid deformation

(from Ryder et al., 2012)



Ryder et al. (2012), Figure 1

- Two earthquakes within 15 minutes of one another
- InSAR shows cumulative deformation but no way to separate events
- Epoch-by-epoch (rather than batch) GPS processing may help...

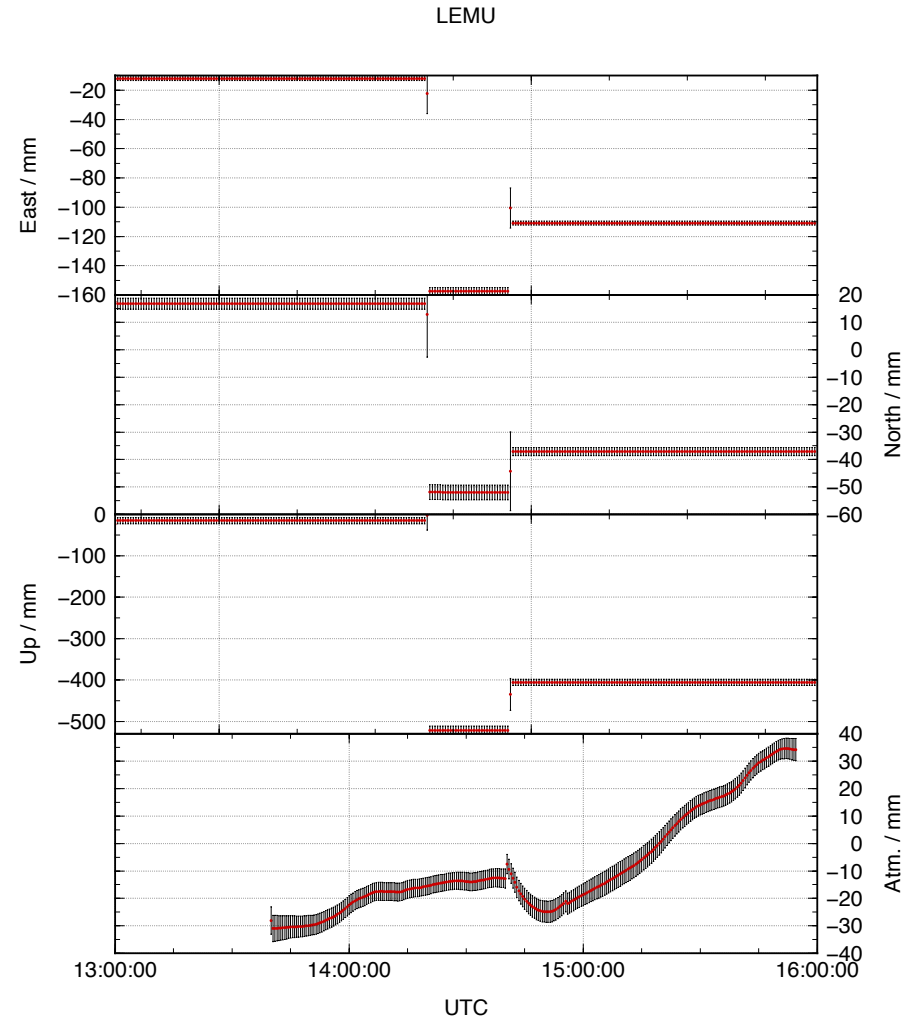
Example 3: First run

Key TRACK commands:

```
site_stats
iloc 0.5 0.5 0.5 0 0 0
lemu 0.5 0.5 0.5 0 0 0
navi 0.5 0.5 0.5 0 0 0
timedep_procs
iloc 1 1 1 2010 03 11 14 39 52 2010 03 11 14 40 00
lemu 1 1 1 2010 03 11 14 39 52 2010 03 11 14 40 00
navi 1 1 1 2010 03 11 14 39 52 2010 03 11 14 40 00
iloc 1 1 1 2010 03 11 14 55 35 2010 03 11 14 56 00
lemu 1 1 1 2010 03 11 14 55 35 2010 03 11 14 56 00
navi 1 1 1 2010 03 11 14 55 35 2010 03 11 14 56 00
```

Second run (updated apr):

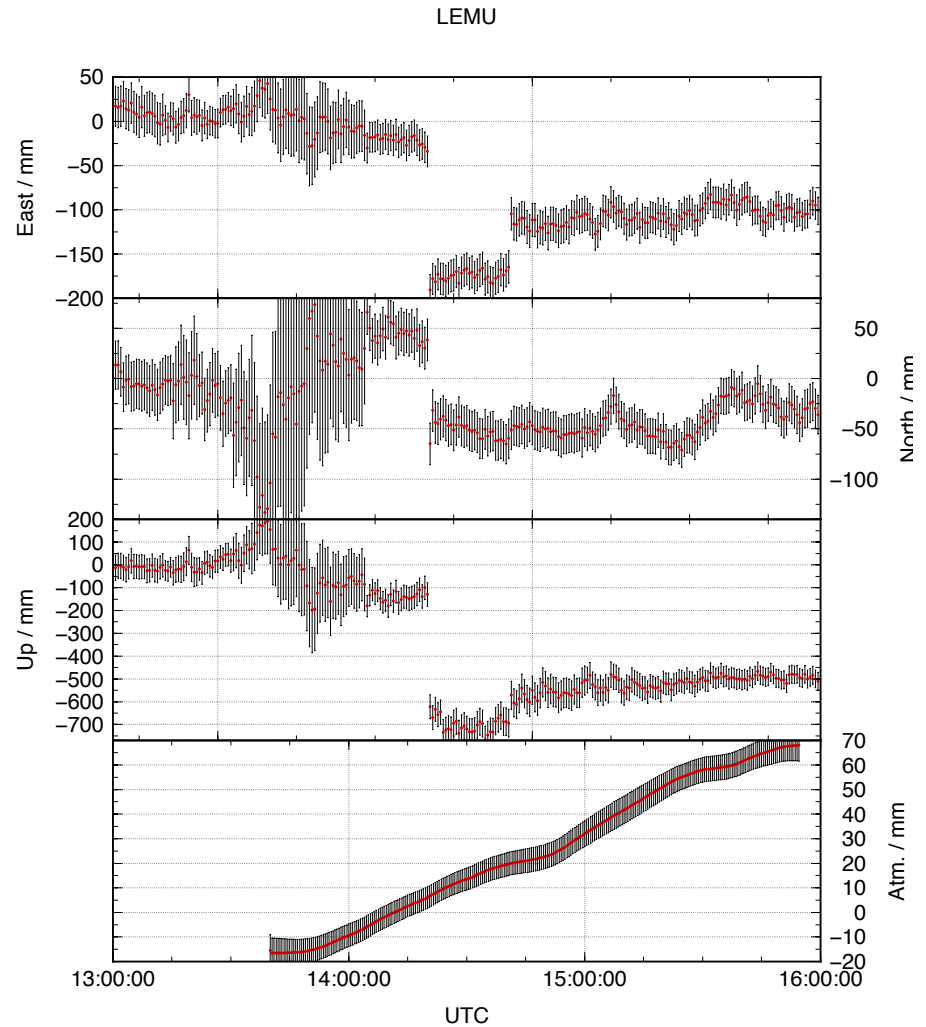
```
site_stats
iloc 0.02 0.02 0.02 0 0 0
lemu 0.02 0.02 0.02 0 0 0
navi 0.02 0.02 0.02 0 0 0
timedep_procs
iloc 1 1 1 2010 03 11 14 39 52 2010 03 11 14 40 00
lemu 1 1 1 2010 03 11 14 39 52 2010 03 11 14 40 00
navi 1 1 1 2010 03 11 14 39 52 2010 03 11 14 40 00
iloc 1 1 1 2010 03 11 14 55 35 2010 03 11 14 56 00
lemu 1 1 1 2010 03 11 14 55 35 2010 03 11 14 56 00
navi 1 1 1 2010 03 11 14 55 35 2010 03 11 14 56 00
site_pos ...
```



Example 3: Final run

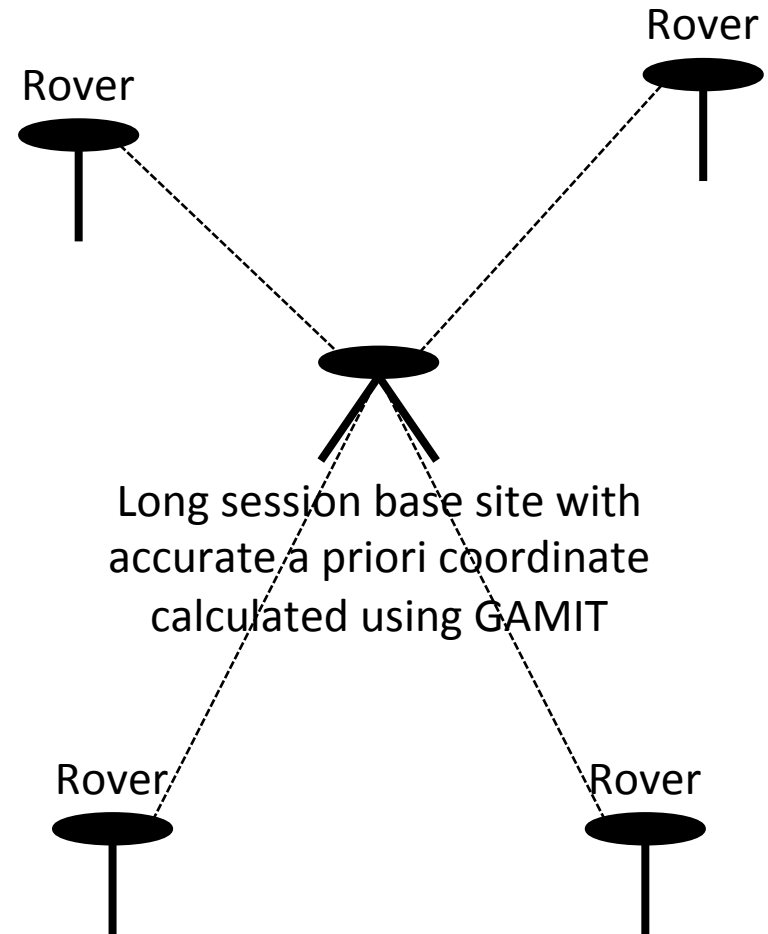
Key TRACK commands:

```
site_stats
  iloc 0.02 0.02 0.02 1 1 1
  lemu 0.02 0.02 0.02 1 1 1
  navi 0.02 0.02 0.02 1 1 1
#timedep_procs
# iloc 1 1 1 2010 03 11 14 39 52 2010 03 11 14 40 00
# lemu 1 1 1 2010 03 11 14 39 52 2010 03 11 14 40 00
# navi 1 1 1 2010 03 11 14 39 52 2010 03 11 14 40 00
# iloc 1 1 1 2010 03 11 14 55 35 2010 03 11 14 56 00
# lemu 1 1 1 2010 03 11 14 55 35 2010 03 11 14 56 00
# navi 1 1 1 2010 03 11 14 55 35 2010 03 11 14 56 00
ambin_file
```

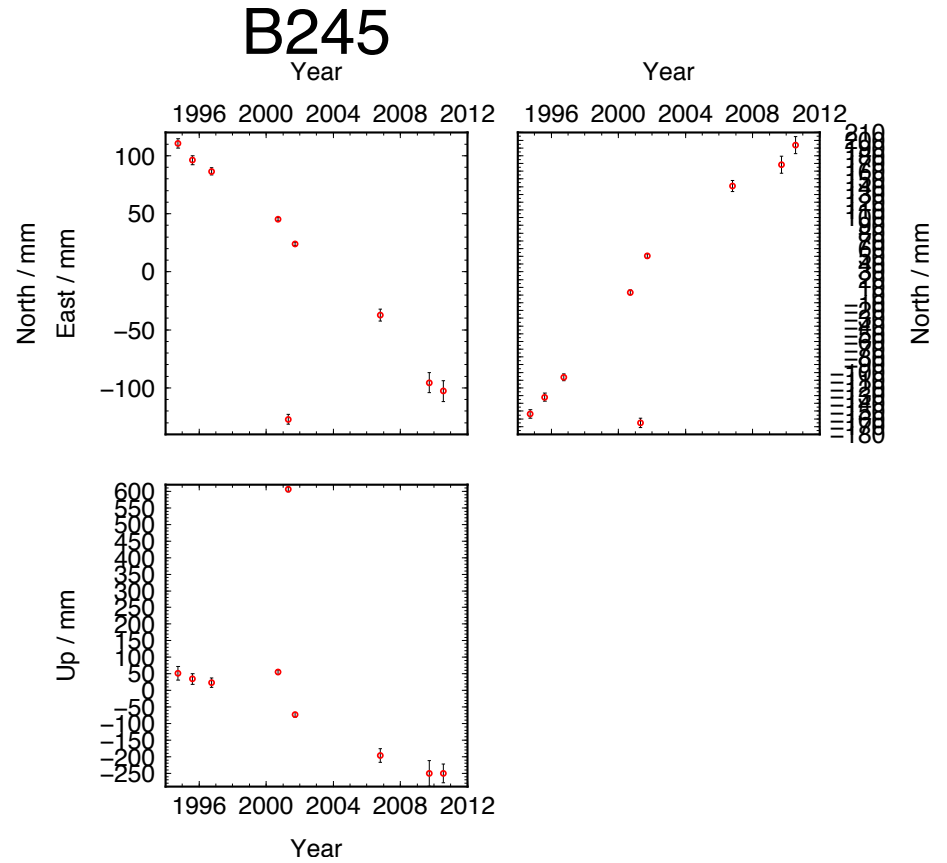
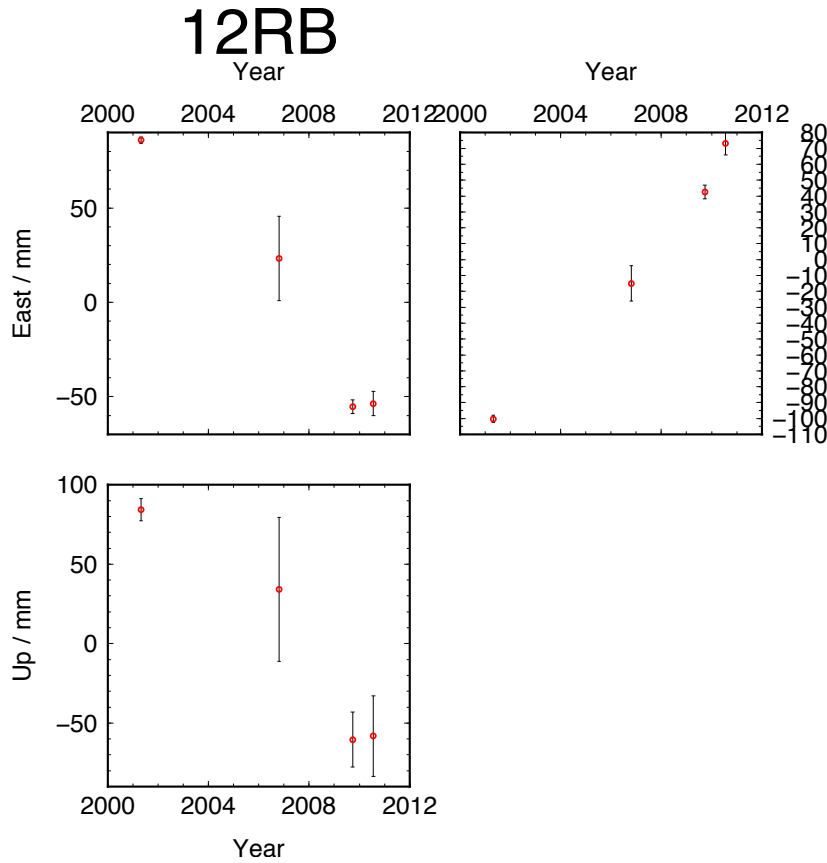


Example 4: Short-static occupations

- Short spans of data (e.g. 30 minutes) may be processed with GAMIT
- Risk of all data being removed during cleaning (AUTCLN) if not high quality
- TRACK may be used in “short-static” approach with fixed, continuously recording and well positioned base site



Example 4: Short-static occupations





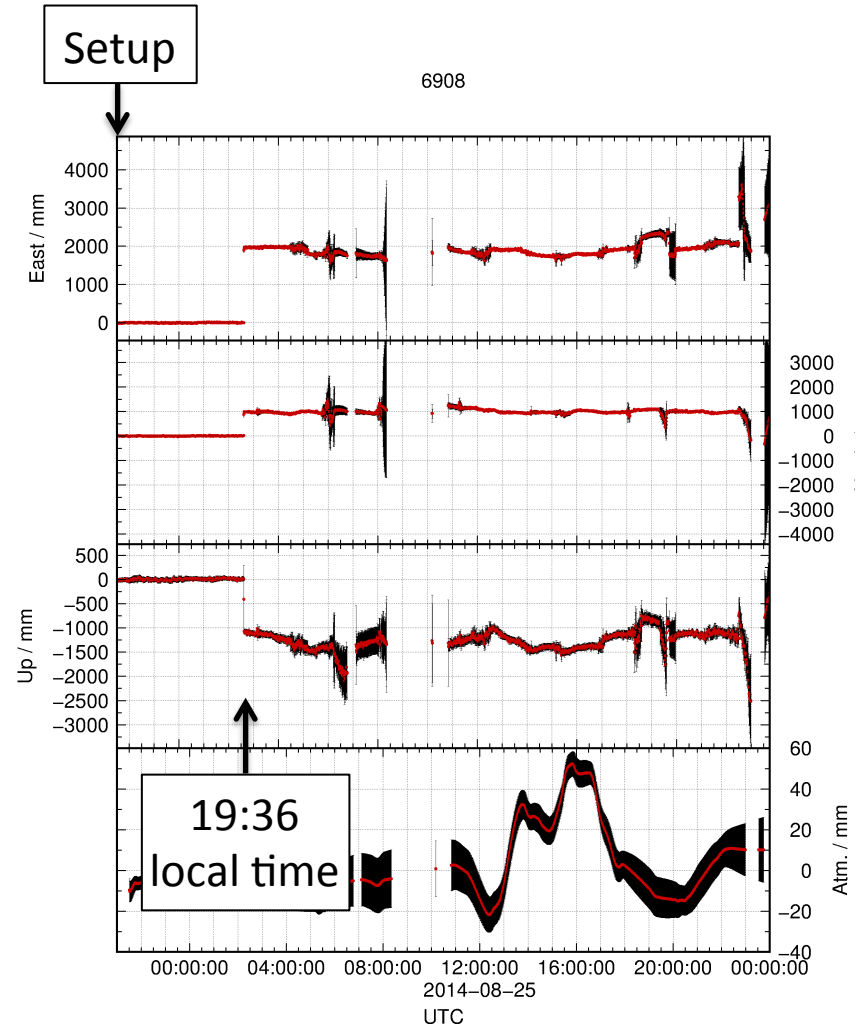
Sometimes, this happens...



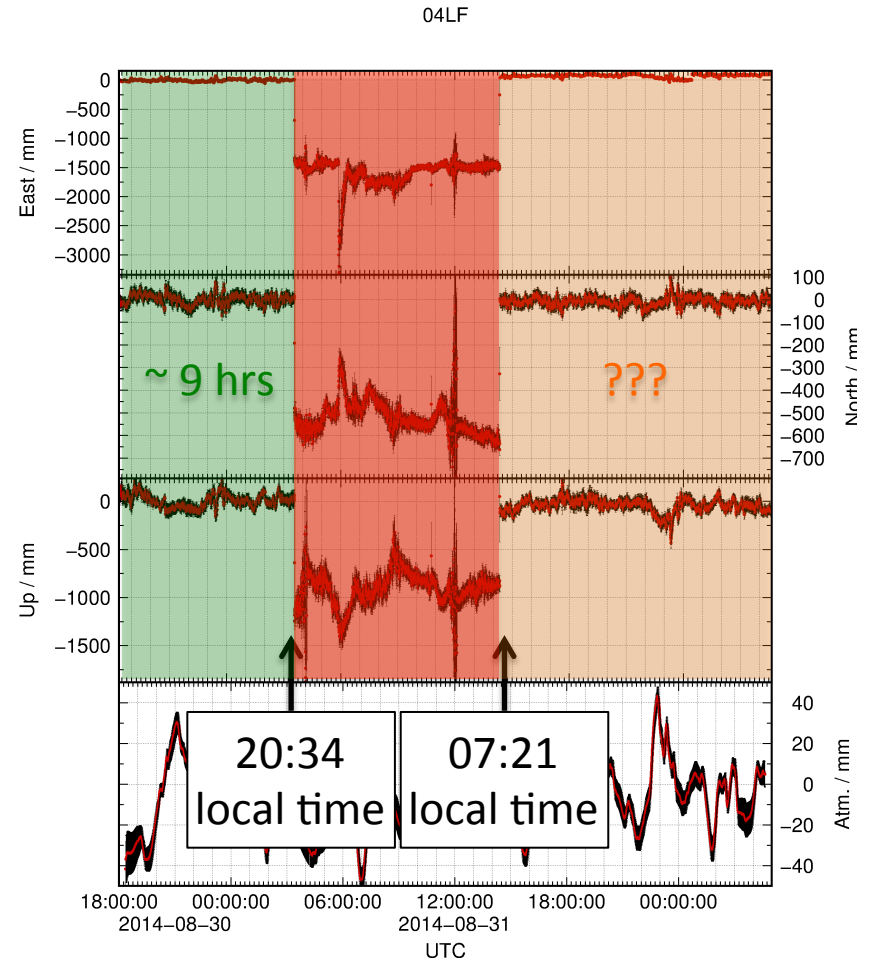
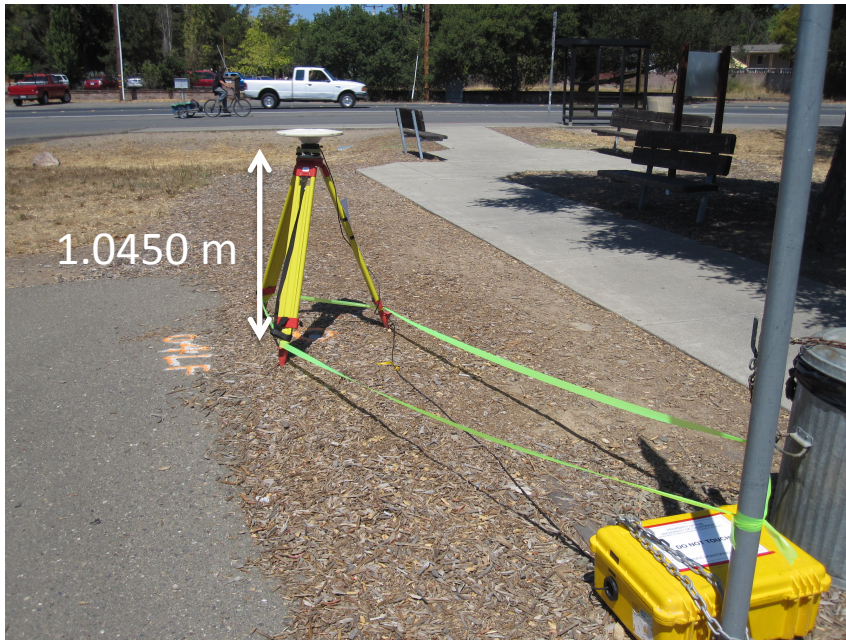
Photographs courtesy of Gareth Funning (University of California, Riverside)

Example 5: Deciphering interference

- First TRACK run with
- Re-run teqc with “-e” option to truncate RINEX file at epoch of disturbance so as not to propagate bad data



Example 5: A complex example



sh_plot_track

- Reads track “NEU”, “DHU” or “XYZ” output file
- May add plot to view evolution of atmospheric delay

sh_kml

- Script for converting several formats of result into KML format for viewing in Google Earth
 - glist (may also be used with time slider)
 - “.org”-file / “.vel”-file
 - track “GEOD”-format output file



References

- England, P. C., R. T. Walker, B. Fu and M. A. Floyd (2013), A bound on the viscosity of the Tibetan crust from the horizontality of palaeolake shorelines, *Earth Planet. Sci. Lett.*, 375, 44–56, [doi:10.1016/j.epsl.2013.05.001](https://doi.org/10.1016/j.epsl.2013.05.001)
- Ryder, I., A. Rietbrock, K. Kelson, R. Bürgmann, M. Floyd, A. Socquet, C. Vigny and D. Carrizo (2012), Large extensional aftershocks in the continental forearc triggered by the 2010 Maule earthquake, Chile, *Geophys. J. Int.*, 188, 879–890, [doi:10.1111/j.1365-246X.2011.05321.x](https://doi.org/10.1111/j.1365-246X.2011.05321.x)

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